

[Turkish Journal of Mathematics](https://journals.tubitak.gov.tr/math)

[Volume 48](https://journals.tubitak.gov.tr/math/vol48) [Number 4](https://journals.tubitak.gov.tr/math/vol48/iss4) [Article 8](https://journals.tubitak.gov.tr/math/vol48/iss4/8) Article 8 Article 8

7-3-2024

New oscillation criteria for first-order differential equations with general delay argument

EMAD R. ATTIA

IRENA JADLOVSKA

Follow this and additional works at: [https://journals.tubitak.gov.tr/math](https://journals.tubitak.gov.tr/math?utm_source=journals.tubitak.gov.tr%2Fmath%2Fvol48%2Fiss4%2F8&utm_medium=PDF&utm_campaign=PDFCoverPages)

C Part of the [Mathematics Commons](https://network.bepress.com/hgg/discipline/174?utm_source=journals.tubitak.gov.tr%2Fmath%2Fvol48%2Fiss4%2F8&utm_medium=PDF&utm_campaign=PDFCoverPages)

Recommended Citation

ATTIA, EMAD R. and JADLOVSKA, IRENA (2024) "New oscillation criteria for first-order differential equations with general delay argument," Turkish Journal of Mathematics: Vol. 48: No. 4, Article 8. <https://doi.org/10.55730/1300-0098.3537>

Available at: [https://journals.tubitak.gov.tr/math/vol48/iss4/8](https://journals.tubitak.gov.tr/math/vol48/iss4/8?utm_source=journals.tubitak.gov.tr%2Fmath%2Fvol48%2Fiss4%2F8&utm_medium=PDF&utm_campaign=PDFCoverPages)

This work is licensed under a [Creative Commons Attribution 4.0 International License](https://creativecommons.org/licenses/by/4.0/). This Research Article is brought to you for free and open access by TÜBİTAK Academic Journals. It has been accepted for inclusion in Turkish Journal of Mathematics by an authorized editor of TÜBİTAK Academic Journals. For more information, please contact pinar.dundar@tubitak.gov.tr.

Turkish Journal of Mathematics

http://journals.tubitak.gov.tr/math/

Turk J Math (2024) 48: 734 – 748 © TÜBİTAK doi:10.55730/1300-0098.3537

Research Article

New oscillation criteria for first-order differential equations with general delay argument

Emad R. ATTIA¹*,*²**, Irena JADLOVSKÁ**³[∗]

¹Department of Mathematics, College of Sciences and Humanities, Prince Sattam Bin Abdulaziz University, Alkharj, Saudi Arabia ²Department of Mathematics, Faculty of Science, Damietta University, New Damietta, Egypt ³Mathematical Institute, Slovak Academy of Sciences, Grešákova 6, Košice, Slovakia

Abstract: This paper is concerned with the oscillation of solutions to a class of first-order differential equations with variable coefficients and a general delay argument. New oscillation criteria are established, which improve and extend many known results reported in the literature. A couple of illustrative examples are given to show the efficiency of the newly obtained results. In particular, it is shown that our criteria partially fulfill a remaining gap in a recent sharp result by Pituk et al. [\[31\]](#page-15-0).

Key words: Oscillation, differential equation, first-order, general delay argument

1. Introduction

In this paper, we are concerned with the oscillation of the first-order delay differential equation

$$
x'(t) + p(t)x(\tau(t)) = 0, \qquad t \ge t_0 \ge 0,
$$
\n(1.1)

where $p, \tau \in C([t_0, \infty), [0, \infty))$, $\tau(t) \leq t$, and $\lim_{t \to \infty} \tau(t) = \infty$.

Equation ([1.1](#page-1-0)) is termed oscillatory if each of its solutions has infinitely many zeros tending to infinity. Otherwise, Eq. ([1.1\)](#page-1-0) is called nonoscillatory. Throughout this paper and without further mention, we shall assume that there exists a nondecreasing continuous function $\theta(t)$ such that $\tau(t) \leq \theta(t)$ for $t \geq t_1$, $t_0 \geq t_1$. Moreover, we will make use of the following notation:

$$
\delta = \lim_{t \to \infty} \int_{\tau(t)}^{t} p(w) \, dw,\tag{1.2}
$$

$$
\delta^* = \lim_{t \to \infty} \int_{\theta(t)}^t p(w) \, dw,\tag{1.3}
$$

and

$$
\rho = \begin{cases} 1, & \delta^* = 0, \\ \lambda(\delta^*) - \epsilon, & \delta^* > 0, \epsilon \in (0, \lambda(\delta^*)), \end{cases}
$$
 (1.4)

where $\lambda(\xi)$ stands for the smaller real root of the equation $\lambda = e^{\lambda \xi}$.

[∗]Correspondence: jadlovska@saske.sk

²⁰¹⁰ *AMS Mathematics Subject Classification:* 34K11; 34K06

ATTIA and JADLOVSKÁ/Turk J Math

In dynamical models, delay and oscillation effects are often formulated by means of external sources and/or nonlinear diffusion, perturbing the natural evolution of related systems; see, e.g., [[24](#page-15-1)[–26](#page-15-2)]. Since the pioneering work of Myshkis [\[28](#page-15-3)], the oscillation theory of delay differential equations has received a great deal of attention, see the monographs $[1, 15, 16]$ $[1, 15, 16]$ $[1, 15, 16]$ $[1, 15, 16]$ $[1, 15, 16]$ $[1, 15, 16]$ as well as the papers cited in this work for a considerable account of results. In particular, oscillation properties of first-order differential equations with delayed argument have numerous applications in the study of higher-order differential equations with deviating arguments; see, e.g., the papers [[3,](#page-14-1) [7,](#page-14-2) [27\]](#page-15-6) for more details.

In view of the classical liminf oscillation criterion

$$
\delta > \frac{1}{e}
$$

due to Koplatadze and Chanturija [[21\]](#page-15-7), it gives sense to consider only the case when

$$
0\leq \delta \leq \frac{1}{\mathrm{e}}.
$$

Most of the research has been done in the case when the delay is nondecreasing. As a starting point, the classical limsup oscillation criterion

$$
\limsup_{t \to \infty} \int_{\tau(t)}^{t} p(w)dw > 1
$$
\n(1.5)

due to Ladas[[23\]](#page-15-8) has commonly been referred. Consequently, major research has been devoted to improving the preceding condition (1.5) (1.5) so that the value at the right-hand side is as close to the threshold value $1/e$ as possible; see, e.g., the papers [[10–](#page-14-3)[13,](#page-14-4) [18–](#page-15-9)[20,](#page-15-10) [22,](#page-15-11) [23,](#page-15-8) [29,](#page-15-12) [30,](#page-15-13) [32](#page-15-14)].

A sharp result in certain sense has been given in [[13,](#page-14-4) Theorem 4] by Gárab, Pituk, and Stavroulakis. It has been proven there that Eq. (1.1) with constant delay and $p(t)$ slowly varying at infinity is oscillatory if *δ >* 0 and

$$
\limsup_{t \to \infty} \int_{\tau(t)}^t p(w) dw > \frac{1}{e}.
$$

For some further works on this particular class of Eq. (1.1) with $p(t)$ enjoying the slowly varying property, see [[12,](#page-14-5) [14,](#page-14-6) [30\]](#page-15-13).

Very recently, Pituk, Stavroulakis and Stavroulakis Jr. [[31\]](#page-15-0) found, for nondecreasing *τ* , the explicit value of the bound at the right-hand side of (1.5) (1.5) (1.5) depending on δ . As a result, they improved condition (1.5) (1.5) and established the oscillation criterion

$$
\limsup_{t \to \infty} \int_{\tau(t)}^{t} p(w)dw > K(\delta), \tag{1.6}
$$

where $\delta \in [0, \frac{1}{e}]$ and

$$
K(\delta) = \begin{cases} 1, & \delta = 0, \\ 2\delta + \frac{2}{\lambda(\delta)} - 1, & \delta \in \left(0, \frac{\ln 2}{2}\right], \\ 2\delta - \frac{2}{\lambda(\delta)} - \frac{1}{\lambda(\delta)} W_{-1}\left(-\frac{\lambda(\delta)}{e^2}\right), & \delta \in \left(\frac{\ln 2}{2}, \frac{1}{e}\right], \end{cases}
$$

where *W−*¹ is the secondary real branch of the Lambert *W* function. It is important to notice that the constant $K(\delta)$ in [\(1.6](#page-2-1)) is sharp in the sense that a nonoscillatory counterexample can be found if

$$
\limsup_{t \to \infty} \int_{\tau(t)}^t p(w) dw \le K(\delta).
$$

In the paper, we confirm (see Example [3.2\)](#page-13-0) that condition (1.6) (1.6) is not necessary for the oscillation of Eq. (1.1) when $\delta = 0$ and that Ladas criterion (1.5) (1.5) can be improved in this case. This finding points out that establishing new oscillation conditions for Eq. (1.1) (1.1) is still of importance.

On the other hand, it is worth noting that the dynamics of solutions of equations with nonmonotone arguments can be completely different from those with monotone ones. As a matter of fact, we recall a remarkable result due to Braverman and Karpuz [[4\]](#page-14-7) who showed that the well-known Ladas criterion [\(1.5\)](#page-2-0) is no longer applicable in the nonmonotone case and there is no constant *L* such that

$$
\limsup_{t \to \infty} \int_{\tau(t)}^t p(w)dw > L
$$

implies Eq. (1.1) to be oscillatory. Consequently, the oscillation problem of Eq. (1.1) with nonmonotone retarded arguments has attracted the interest of many mathematicians and both iterative and noniterative oscillation criteria have been established; see, e.g, the papers [[2,](#page-14-8) [4](#page-14-7)[–6](#page-14-9), [9](#page-14-10), [17](#page-15-15), [22\]](#page-15-11) and those cited therein. For an easy reference, we give a brief summary of some recently published oscillation results.

In 2015, Infante, Koplatadze and Stavroulakis [[17\]](#page-15-15) proved that Eq. [\(1.1](#page-1-0)) is oscillatory if

$$
\limsup_{t \to \infty} \int_{\theta(t)}^t p(w) e^{\int_{\tau(w)}^{\theta(t)} p(w_1) e^{\int_{\tau(w_1)}^{\theta(t)} p(w_2) dw_2} dw_1} dw > 1,
$$
\n(1.7)

or

$$
\limsup_{\epsilon \to 0^+} \left(\limsup_{t \to \infty} \int_{\theta(t)}^t p(w) e^{(\lambda(\delta) - \epsilon) \int_{\tau(w)}^{\theta(t)} p(w_1) dw_1} dw \right) > 1.
$$
\n(1.8)

In 2020, Chatzarakis and Jadlovská [[5\]](#page-14-11) established the condition

$$
\limsup_{t \to \infty} \int_{\varphi(t)}^{t} p(w) e^{\int_{\tau(w)}^{\varphi(t)} p(w_1) e^{\int_{\tau(w_1)}^{w_1} \Psi_n(w_2) dw_2} dw_1} dw > 1,
$$
\n(1.9)

where

and

$$
\varphi(t) = \sup_{u \le t} \tau(u) \tag{1.10}
$$

$$
\Psi_0(t) = p(t) \left(1 + \int_{\tau(t)}^t p(w) e^{\int_{\tau(w)}^t p(w_1) e^{\lambda(\delta) \int_{\tau(w_1)}^w p(w_2) dw_2} dw_1} dw \right),
$$

\n
$$
\Psi_n(t) = p(t) \left(1 + \int_{\tau(t)}^t p(w) e^{\int_{\tau(w)}^t p(w_1) e^{\int_{\tau(w_1)}^w \Psi_{n-1}(w_2) dw_2} dw_1} dw \right), \quad n = 1, 2,
$$

In 2022, Attia and El-Morshedy [[2\]](#page-14-8) obtained the condition

$$
\limsup_{t \to \infty} \left(\sum_{r=1}^{n} \left(\prod_{r_1=2}^{r} C\left(\theta^{r_1-1}(t)\right) \right) \Omega_r^n(t) \right) > 1 - B(\delta^*), \quad n \in \mathbb{N}, \tag{1.11}
$$

where

$$
B(\delta^*) = \frac{1 - \delta^* - \sqrt{1 - 2\delta^* - {\delta^*}^2}}{2}, \quad 0 \le \delta^* \le \frac{1}{e},
$$

$$
C(t) = \frac{1}{1 - \int_{\theta(t)}^t p(w_1) \exp\left(\int_{\tau(w_1)}^{\theta(t)} \frac{p(w_2)}{1 - \Omega_1^1(w_2)} dw_2\right) dw_1}
$$

and

$$
\Omega_i^n(t) = \int_{\theta(t)}^t p(w_1) \int_{\tau(w_1)}^{\theta(t)} p(w_2) \int_{\tau(w_2)}^{\theta^2(t)} \dots \int_{\tau(w_{i-1})}^{\theta^{i-1}(t)} p(w_i) dw_i \ dw_{i-1} \dots \ dw_1, \quad i = 1, \dots, n-1,
$$

$$
\Omega_n^n(t) = \int_{\theta(t)}^t p(w_1) \int_{\tau(w_1)}^{\theta(t)} p(w_2) \int_{\tau(w_2)}^{\theta^2(t)} \dots \int_{\tau(w_{n-1})}^{\theta^{n-1}(t)} p(w_n) e^{\rho \int_{\tau(w_n)}^{\theta^n(t)} p(w_{n+1}) dw_{n+1}} dw_n \ dw_{n-1} \dots \ dw_1.
$$

The objective of this work is to obtain new oscillation criteria for Eq. (1.1) (1.1) , which would improve the above mentioned ones in both cases of monotone and nonmonotone arguments. Two illustrative examples are presented to demonstrate the power and efficiency of our results.

2. Main results

We start with the following lemmas, which will be of utmost importance in establishing our main results. All our results are formulated in terms of constants (1.2) – (1.4) (1.4) (1.4) .

Lemma 2.1 (see [\[11,](#page-14-12) Lemma 2.1.2] and [\[2](#page-14-8), Lemma 2.1]) *Assume that* $x(t)$ *is an eventually positive solution of Eq. [\(1.1](#page-1-0)). Then*

$$
\frac{x(\theta(t))}{x(t)} \ge \rho \quad \text{for all sufficiently large } t. \tag{2.1}
$$

Lemma 2.2 *Assume that* $x(t)$ *is an eventually positive solution of Eq. [\(1.1\)](#page-1-0) and there exists a continuous positive function* $Q_0(t)$ *such that*

$$
\frac{x(\tau(t))}{x(t)} \ge Q_0(t). \tag{2.2}
$$

Then, for any $n \in \mathbb{N}$ *and t sufficiently large,*

$$
\frac{x(\tau(t))}{x(t)} \ge Q_n(t),\tag{2.3}
$$

where

$$
Q_n(t) = \frac{e^{\int_{\tau(t)}^{\theta(t)} p(w)Q_{n-1}(w)dw}}{1 - \int_{\theta(t)}^t p(w) e^{\int_{\tau(w)}^{\theta(t)} p(w_1)Q_{n-1}(w_1)dw_1}dw}.
$$
\n(2.4)

Proof Integrating ([1.1](#page-1-0)) from $\theta(t)$ to *t*, we obtain

$$
x(t) - x(\theta(t)) + \int_{\theta(t)}^{t} p(w)x(\tau(w))dw = 0.
$$
 (2.5)

Dividing [\(1.1](#page-1-0)) by $x(t)$ and integrating the resulting inequality from *w* to *t*, $t \geq w$, we have

$$
x(w) = x(t)e^{\int_w^t p(w_1)\frac{x(\tau(w_1))}{x(w_1)}dw_1}.
$$
\n(2.6)

This, together with [\(2.5](#page-5-0)), leads to

$$
x(t) - x(\theta(t)) + x(\theta(t)) \int_{\theta(t)}^{t} p(w) e^{\int_{\tau(w)}^{\theta(t)} p(w_1) \frac{x(\tau(w_1))}{x(w_1)} dw_1} dw = 0.
$$
 (2.7)

Therefore,

$$
\frac{x(\theta(t))}{x(t)} = \frac{1}{1 - \int_{\theta(t)}^t p(w) e^{\int_{\tau(w)}^{\theta(t)} p(w_1) \frac{x(\tau(w_1))}{x(w_1)} dw_1} dw}.
$$
\n(2.8)

From (2.6) (2.6) , we see that

$$
\frac{x(\tau(t))}{x(t)} = \frac{x(\tau(t))}{x(\theta(t))} \frac{x(\theta(t))}{x(t)} = \frac{e^{\int_{\tau(t)}^{\theta(t)} p(w) \frac{x(\tau(w))}{x(w)}} dw}{1 - \int_{\theta(t)}^t p(w) e^{\int_{\tau(w)}^{\theta(t)} p(w_1) \frac{x(\tau(w_1))}{x(w_1)} dw_1} dw},
$$
\n(2.9)

which in view of (2.8) (2.8) (2.8) leads to

$$
\frac{x(\tau(t))}{x(t)} \geq \frac{e^{\int_{\tau(t)}^{\theta(t)} p(w)Q_0(w)dw}}{1 - \int_{\theta(t)}^t p(w) e^{\int_{\tau(w)}^{\theta(t)} p(w_1)Q_0(w_1)dw_1}dw} = Q_1(t). \tag{2.10}
$$

Substituting again (2.10) (2.10) into (2.9) (2.9) we get

$$
\frac{x(\tau(t))}{x(t)} \ge \frac{e^{\int_{\tau(t)}^{\theta(t)} p(w)Q_1(w)dw}}{1 - \int_{\theta(t)}^t p(w) e^{\int_{\tau(w)}^{\theta(t)} p(w_1)Q_1(w_1)dw_1}dw} = Q_2(t).
$$

A simple induction completes the proof. \Box

Lemma 2.3 *Assume that* $\delta^* > 0$ *and* $x(t)$ *is an eventually positive solution of Eq. [\(1.1](#page-1-0)). If*

$$
\liminf_{t \to \infty} \int_{\theta(t)}^t p(w) \int_{\tau(w)}^{\theta(t)} p(w_1) e^{(\lambda(\delta^*) - \epsilon) \int_{\tau(w_1)}^{\theta^2(t)} p(w_2) dw_2} dw_1 dw \ge \beta > 0
$$
\n(2.11)

for some $\epsilon \in (0, \lambda(\delta^*))$ *, then*

$$
\liminf_{t \to \infty} \frac{x(t)}{x(\theta(t))} \ge \frac{1 - \delta^* - \sqrt{(1 - \delta^*)^2 - 4\beta}}{2}.
$$
\n(2.12)

Proof First, we claim that

$$
\frac{x(\theta(t))}{x(\theta^2(t))} > \frac{R(t)}{1 - \int_{\theta(t)}^t p(w)dw} \quad \text{ for all sufficiently large } t,
$$
\n(2.13)

where $\theta^2(t) = \theta(\theta(t))$ and

$$
R(t) = \int_{\theta(t)}^t p(w) \int_{\tau(w)}^{\theta(t)} p(w_1) e^{(\lambda(\delta^*) - \epsilon) \int_{\tau(w_1)}^{\theta^2(t)} p(w_2) dw_2} dw_1 dw.
$$

Integrating [\(1.1](#page-1-0)) from $\tau(w)$ to $\theta(t)$ for $\theta(t) \leq w \leq t$, we get

$$
x(\theta(t)) - x(\tau(w)) + \int_{\tau(w)}^{\theta(t)} p(w_1)x(\tau(w_1))dw_1 = 0.
$$

Substituting this into (2.5) (2.5) (2.5) , we obtain

$$
x(t) - x(\theta(t)) + x(\theta(t)) \int_{\theta(t)}^t p(w)dw + \int_{\theta(t)}^t p(w) \int_{\tau(w)}^{\theta(t)} p(w_1)x(\tau(w_1))dw_1 dw = 0.
$$
 (2.14)

In view of $\theta^2(t) \ge \tau(w_1)$ for $\tau(w) \le w_1 \le \theta(t)$ and $\theta(t) \le w \le t$, it follows from ([2.6\)](#page-5-1) that

$$
x(\tau(w_1)) = x(\theta^2(t)) e^{\int_{\tau(w_1)}^{\theta^2(t)} p(w_2) \frac{x(\tau(w_2))}{x(w_2)} dw_2}.
$$

Substituting into (2.14) , we obtain

$$
x(t) - x(\theta(t)) + x(\theta(t)) \int_{\theta(t)}^{t} p(w) dw
$$

+ $x(\theta^2(t)) \int_{\theta(t)}^{t} p(w) \int_{\tau(w)}^{\theta(t)} p(w_1) e^{\int_{\tau(w_1)}^{\theta^2(t)} p(w_2) \frac{x(\tau(w_2))}{x(w_2)} dw_2} dw_1 dw = 0.$ (2.15)

Using Lemma [2.1](#page-4-0) and $\delta^* > 0$, we obtain

$$
x(\theta(t)) \ge x(t) + x(\theta(t)) \int_{\theta(t)}^t p(w)dw
$$

+ $x(\theta^2(t)) \int_{\theta(t)}^t p(w) \int_{\tau(w)}^{\theta(t)} p(w_1) e^{\int_{\tau(w_1)}^{\theta^2(t)} p(w_2)(\lambda(\delta^*) - \epsilon)dw_2} dw_1 dw,$ (2.16)

where $\epsilon > 0$ is sufficiently small. Consequently,

$$
\frac{x(\theta(t))}{x(\theta^2(t))} > \frac{\int_{\theta(t)}^t p(w) \int_{\tau(w)}^{\theta(t)} p(w_1) e^{\int_{\tau(w_1)}^{\theta^2(t)} p(w_2) (\lambda(\delta^*) - \epsilon) dw_2} dw_1 dw}{1 - \int_{\theta(t)}^t p(w) dw}
$$

$$
= \frac{R(t)}{1 - \int_{\theta(t)}^t p(w) dw}.
$$

This completes the proof of [\(2.13](#page-6-1)) and so our claim holds. Now we will prove ([2.12\)](#page-5-5). Assume that $0 < \delta^{**} < \delta^*$ and $0 < \beta^* < \beta$ are, respectively, any two numbers arbitrarily close to δ^* and β . Then there exists *T* large enough so that

$$
\int_{\theta(t)}^t p(w)dw > \delta^{**} \quad \text{ for } t > T
$$

and

$$
\int_{\theta(t)}^t p(w) \int_{\tau(w)}^{\theta(t)} p(w_1) e^{\int_{\tau(w_1)}^{\theta^2(t)} p(w_2)(\lambda(\delta^*) - \epsilon) dw_2} dw_1 dw > \beta^* \quad \text{ for } t > T.
$$

Substituting both the above estimates into (2.16) (2.16) , we obtain

$$
x(\theta(t)) > x(t) + \delta^{**}x(\theta(t)) + \beta^*x(\theta^2(t)).
$$
\n(2.17)

Consequently,

$$
x(\theta(t)) > b_1 x(\theta^2(t)),\tag{2.18}
$$

where

$$
b_1 = \frac{\beta^*}{1 - \delta^{**}}.
$$

Let $T_1 > T$ such that $t = \theta(T_1)$, and so

$$
\int_t^{T_1} p(w)dw > \delta^{**}
$$

and

$$
\int_t^{T_1} p(w) \int_{\tau(w)}^t p(w_1) e^{\int_{\tau(w_1)}^{\theta(t)} p(w_2)(\lambda(\delta) - \epsilon) dw_2} dw_1 dw > \beta^*.
$$

By integrating Eq. (1.1) from t to T_1 , and using the same arguments as above we obtain

$$
x(t) > b_1 x(\theta(t)).\tag{2.19}
$$

From this and (2.17) (2.17) (2.17) , we get

$$
x(\theta(t)) > b_2 x(\theta^2(t)),
$$

where

$$
b_2 = \frac{\beta^*}{1 - b_1 - \delta^{**}}.
$$

Repeating this procedure we have

$$
x(\theta(t)) > b_n x(\theta^2(t)),
$$

where

$$
b_n = \frac{\beta^*}{1 - b_{n-1} - \delta^{**}}.
$$

Since ${b_n}_{n\geq 1}$ is strictly increasing and bounded, then

$$
b^2 - (1 - \delta^{**}) b + \beta^* = 0,
$$

where

$$
\lim_{n \to \infty} b_n = b.
$$

Therefore,

$$
\frac{x(\theta(t))}{x(\theta^2(t))} \ge \frac{1 - \delta^{**} - \sqrt{(1 - \delta^{**})^2 - 4\beta^*}}{2}
$$

for all sufficiently large *t*. Then, we see that

$$
\liminf_{t \to \infty} \frac{x(\theta(t))}{x(\theta^2(t))} \ge \frac{1 - \delta^{**} - \sqrt{\left(1 - \delta^{**}\right)^2 - 4\beta^*}}{2}
$$

.

Letting $\delta^{**} \to \delta^*$ and $\beta^* \to \beta$ the last inequality implies that

$$
\liminf_{t \to \infty} \frac{x(t)}{x(\theta(t))} = \liminf_{t \to \infty} \frac{x(\theta(t))}{x(\theta^2(t))} \ge \frac{1 - \delta^* - \sqrt{(1 - \delta^*)^2 - 4\beta}}{2}.
$$

The proof is complete. **□**

Remark 2.4 *It is clear for* $\delta^* > 0$ *that*

$$
\int_{\theta(t)}^t p(w) \int_{\tau(w)}^{\theta(t)} p(w_1) e^{(\lambda(\delta^*)-\epsilon) \int_{\theta(w_1)}^{\theta^2(t)} p(w_2) dw_2} dw_1 dw \ge \int_{\theta(t)}^t p(w) \int_{\theta(w)}^{\theta(t)} p(w_1) dw_1 dw.
$$

By using similar arguments as in the proof of [[11,](#page-14-12) Lemma 2.1.3], we arrive at

$$
\liminf_{t\to\infty}\int_{\theta(t)}^t p(w)\int_{\tau(w)}^{\theta(t)} p(w_1)e^{(\lambda(\delta^*)-\epsilon)\int_{\theta(w_1)}^{\theta^2(t)} p(w_2)dw_2}dw_1dw \geq \frac{1}{2}\delta^{*2}.
$$

As a result, in Lemma [2.3](#page-5-6), one can choose $\beta = \frac{1}{2}\delta^{*2}$ *. Consequently,*

$$
\frac{1 - \delta^* - \sqrt{(1 - \delta^*)^2 - 4\beta}}{2} = \frac{1 - \delta^* - \sqrt{1 - 2\delta^* - {\delta^*}^2}}{2}.
$$

Therefore, we see that Lemma [2.3](#page-5-6) improves [[11,](#page-14-12) Lemma 2.1.3].

Now we are prepared to state the main results of the paper.

Theorem 2.5 *Assume that* $\delta^* > 0$ *and there exists* $\beta > 0$ *satisfying* ([2.20\)](#page-8-0) *for some* $\epsilon \in (0, \lambda(\delta^*))$ *. If for some* $n \in \mathbb{N}_0$

$$
\limsup_{t \to \infty} \int_{\theta(t)}^{t} p(w) e^{\int_{\tau(w)}^{\theta(t)} Q_n(w_1) p(w_1) dw_1} dw > 1 - \frac{1 - \delta^* - \sqrt{(1 - \delta^*)^2 - 4\beta}}{2}, \tag{2.20}
$$

where $Q_0(t) = \lambda(\delta^*) - \epsilon$ and $\{Q_n(t)\}_{n \in \mathbb{N}}$ is defined by (2.4) , then Eq. ([1.1\)](#page-1-0) is oscillatory.

Proof Assume the contrary and let $x(t)$ be a nonoscillatory solution of Eq. ([1.1\)](#page-1-0). Without loss of generality assume that $x(t)$ is eventually positive. By (2.7) from the proof of Lemma [2.2](#page-4-2), we have

$$
x(t) - x(\theta(t)) + x(\theta(t)) \int_{\theta(t)}^{t} p(w) e^{\int_{\tau(w)}^{\theta(t)} p(w_1) \frac{x(\tau(w_1))}{x(w_1)} dw_1} dw = 0.
$$
 (2.21)

According to Lemma [2.1](#page-4-0) and the nonincreasing nature of $x(t)$, we have, for any $\epsilon \in (0, \lambda(\delta^*))$ and t sufficiently large,

$$
\frac{x(\tau(t))}{x(t)} \ge \frac{x(\theta(t))}{x(t)} \ge \lambda(\delta^*) - \epsilon = Q_0(t).
$$

By Lemma [2.2,](#page-4-2) we are led to

$$
\frac{x(\tau(t))}{x(t)} \ge Q_n(t), \quad n \in \mathbb{N}_0.
$$
\n(2.22)

Substituting (2.22) (2.22) into (2.21) (2.21) , we have

$$
\int_{\theta(t)}^{t} p(w) e^{\int_{\tau(w)}^{\theta(t)} p(w_1) Q_n(w_1) dw_1} dw \le 1 - \frac{x(t)}{x(\theta(t))}.
$$
\n(2.23)

Therefore,

$$
\limsup_{t\to\infty}\int_{\theta(t)}^t p(w) e^{\int_{\tau(w)}^{\theta(t)} p(w_1)Q_n(w_1)dw_1} dw \leq 1 - \liminf_{t\to\infty}\frac{x(t)}{x(\theta(t))}.
$$

From this and (2.12) (2.12) (2.12) , we obtain a contradiction to (2.20) . The proof of the theorem is complete. \Box

Theorem 2.6 *Assume that* $\theta(t)$ *is strictly increasing. If there exist* $n \in \mathbb{N}_0$ *and an unbounded sequence* ${r_l}_{l \in \mathbb{N}_0}$ *such that*

$$
\int_{\theta(r_l)}^{r_l} p(w) e^{\int_{\tau(w)}^{\theta(r_l)} Q_n(w_1) p(w_1) dw_1} dw \ge 1 - \frac{\int_{r_l}^{\theta^{-1}(r_l)} p(w) \int_{\tau(w)}^{r_l} p(w_1) e^{\int_{\tau(w_1)}^{\theta(r_l)} p(w_2) Q_n(w_2) dw_2} dw_1 dw}{1 - \int_{r_l}^{\theta^{-1}(r_l)} p(w) dw},
$$
\n(2.24)

where θ^{-1} denotes the inverse of θ , $Q_0(t) = \rho$ and $\{Q_n(t)\}_{n \in \mathbb{N}}$ is defined by (2.4) (2.4) , then Eq. [\(1.1\)](#page-1-0) is oscillatory.

Proof Assume the contrary and let $x(t)$ be a nonoscillatory solution of Eq. (1.1) (1.1) . Without loss of generality assume that $x(t)$ is eventually positive. By (2.7) from the proof of Lemma [2.2](#page-4-2), we have

$$
x(t) - x(\theta(t)) + x(\theta(t)) \int_{\theta(t)}^{t} p(w) e^{\int_{\tau(w)}^{\theta(t)} p(w_1) \frac{x(\tau(w_1))}{x(w_1)} dw_1} dw = 0.
$$
 (2.25)

By using the nonincreasing nature of $x(t)$ and Lemma [2.1](#page-4-0), we obtain

$$
\frac{x(\tau(t))}{x(t)} \ge \frac{x(\theta(t))}{x(t)} \ge \rho = Q_0(t).
$$

By Lemma [2.2](#page-4-2) , we are led to

$$
\frac{x(\tau(t))}{x(t)} \ge Q_n(t), \quad n \in \mathbb{N}_0.
$$
\n(2.26)

Substituting into [\(2.25\)](#page-9-2), we get

$$
\int_{\theta(t)}^{t} p(w) e^{\int_{\tau(w)}^{\theta(t)} p(w_1) Q_n(w_1) dw_1} dw \le 1 - \frac{x(t)}{x(\theta(t))}
$$
\n(2.27)

for all sufficiently large *t*. By (2.15) (2.15) (2.15) and $x(t) > 0$, we have

$$
\frac{x(\theta(t))}{x(\theta^2(t))} > \frac{\int_{\theta(t)}^t p(w) \int_{\tau(w)}^{\theta(t)} p(w_1) e^{\int_{\tau(w_1)}^{\theta^2(t)} p(w_2) \frac{x(\tau(w_2))}{x(w_2)} dw_2} dw_1 dw}{1 - \int_{\theta(t)}^t p(w) dw}.
$$

From the above inequality, (2.26) (2.26) (2.26) and the strictly increasing nature of $\theta(t)$, we obtain

$$
\frac{x(t)}{x(\theta(t))} > \frac{\int_t^{\theta^{-1}(t)} p(w) \int_{\tau(w)}^t p(w_1) e^{\int_{\tau(w_1)}^{\theta(t)} p(w_2) Q_n(w_2) dw_2} dw_1 dw}{1 - \int_t^{\theta^{-1}(t)} p(w) dw}.
$$

This together with ([2.27](#page-10-0)) implies that

$$
\int_{\theta(t)}^t p(w) e^{\int_{\tau(w)}^{\theta(t)} p(w_1) Q_n(w_1) dw_1} dw < 1 - \frac{\int_t^{\theta^{-1}(t)} p(w) \int_{\tau(w)}^t p(w_1) e^{\int_{\tau(w_1)}^{\theta(t)} p(w_2) Q_n(w_2) dw_2} dw_1 dw}{1 - \int_t^{\theta^{-1}(t)} p(w) dw}
$$

for all sufficiently large t , which contradicts (2.24) (2.24) (2.24) and completes the proof of the theorem. \Box

3. Numerical examples

In this section, we give two examples illustrating the applications of our results, showing their strength in both cases of monotone and nonmonotone delays.

Example 3.1 Consider the differential equation

$$
x'(t) + p(t)x(\tau(t)) = 0, \quad t \ge 1,
$$
\n(3.1)

where

$$
\tau(t) = \begin{cases}\n t - 1 & \text{if } t \in [2l, 2l + 1] \\
-t + 4l + 1 & \text{if } t \in [2l + 1, 2l + 1.001] \\
\frac{1001}{999}t - \frac{4}{999}l - \frac{1003}{999} & \text{if } t \in [2l + 1.001, 2l + 2]\n\end{cases}, \quad l \in \mathbb{N}_0,
$$

and

$$
p(t) = \begin{cases} \frac{1}{e} & \text{if } t \in [c_i, d_i] \\ (\mu - \frac{1}{e}) (t - d_i) + \frac{1}{e} & \text{if } t \in [d_i, d_i + 1] \\ \mu & \text{if } t \in [d_i + 1, d_i + 5] \\ \frac{(\frac{1}{e} - \mu)(t - d_i - 5)}{c_{i+1} - d_i - 5} + \mu & \text{if } t \in [d_i + 5, c_{i+1}] \end{cases}, \quad i \in \mathbb{N}_0,
$$

where $\mu \geq \frac{1}{e}$ and $\{d_i\}$ is a sequence of positive integers such that $d_i > c_i + 3$, $c_{i+1} > d_i + 5$ and $\lim_{i \to \infty} c_i = \infty$. Let $\theta(t) = t - 1$. It is clear that

$$
t - 1.002 \le \tau(t) \le t - 1
$$

and

$$
\delta = \liminf_{t \to \infty} \int_{\tau(t)}^t p(w) dw = \liminf_{t \to \infty} \int_{\theta(t)}^t p(w) dw = \lim_{i \to \infty} \int_{\theta(d_i)}^{\theta_i} p(w) dw = \frac{1}{e} = \delta^*.
$$

It follows that $\lambda(\delta) = e$. Let

$$
R(t) = \int_{\theta(t)}^t p(w) \int_{\tau(w)}^{\theta(t)} p(w_1) e^{(\lambda(\delta^*) - \epsilon) \int_{\tau(w_1)}^{\theta^2(t)} p(w_2) dw_2} dw_1 dw.
$$

Therefore,

$$
\liminf_{t \to \infty} R(t) = \lim_{i \to \infty} \int_{\theta(d_i)}^{d_i} p(w) \int_{\tau(w)}^{\theta(d_i)} p(w_1) e^{(\lambda(\delta) - \epsilon) \int_{\tau(w_1)}^{\theta^2(d_i)} p(w_2) dw_2} dw_1 dw
$$
\n
$$
\geq \lim_{i \to \infty} \int_{d_i - 1}^{d_i} \frac{1}{e} \int_{w - 1}^{\theta(d_i)} \frac{1}{e} e^{(\lambda(\delta) - \epsilon) \int_{w_1 - 1}^{d_i - 2} \frac{1}{e} dw_2} dw_1 dw
$$
\n
$$
= \frac{e^{\frac{\lambda(\delta) - \epsilon}{e}} - \frac{\lambda(\delta) - \epsilon}{e} - 1}{(\lambda(\delta) - \epsilon)^2} > 0.09719 = \beta,
$$

where we put $\epsilon = 0.001$. Let

$$
L(t) = \int_{\theta(t)}^{t} p(w) e^{\int_{\tau(w)}^{\theta(t)} Q_1(w_1) p(w_1)} dw.
$$

Then

$$
L(d_i + 5)
$$
\n
$$
\geq \int_{\theta(d_i+5)}^{d_i+5} p(w) \exp\left(\int_{w-1}^{\theta(d_i+5)} \frac{p(w_1) \exp\left(\int_{w_1-1}^{w_1-1} p(w_2) dw_2\right)}{1 - \int_{w_1-1}^{w_1} p(w_2) \exp\left(\int_{w_2-1}^{w_1-1} p(w_3) Q_0(w_3) dw_3\right) dw_2}\right) dw
$$
\n
$$
\geq \int_{d_i+4}^{d_i+5} p(w) \exp\left(\int_{w-1}^{d_i+4} \frac{p(w_1)}{1 - \int_{w_1-1}^{w_1} p(w_2) \exp\left(\int_{w_2-1}^{w_1-1} p(w_3) \left(\lambda(\delta) - \epsilon\right) dw_3\right) dw_2}\right) dw
$$
\n
$$
= \frac{\left(e^{D\left(-\left(\lambda(\delta) - \epsilon\right) + e^{\left(\lambda(\delta) - \epsilon\right)\mu}\right)} - \left(\lambda(\delta) - \epsilon\right)e^D - e^D - e^{\left(\lambda(\delta) - \epsilon\right)\mu} + \left(\lambda(\delta) - \epsilon\right) + 1\right)e^{-D}}{\left(\lambda(\delta) - \epsilon\right)},
$$

where

$$
D = \frac{(\lambda(\delta) - \epsilon)\,\mu}{e^{(\lambda(\delta) - \epsilon)\mu} - (\lambda(\delta) - \epsilon) - 1}.
$$

Consequently,

$$
\limsup_{t \to \infty} L(t) = \lim_{i \to \infty} L(d_i + 5) > 0.74 > 1 - \frac{1 - \delta - \sqrt{(1 - \delta)^2 - 4\beta}}{2}
$$

for $\mu = \frac{1}{e} + 0.01666$, which means that the condition ([2.20](#page-8-0)) with $n = 1$ of Theorem [2.5](#page-8-1) is satisfied. Therefore, every solution of [\(3.1\)](#page-10-1) is oscillatory. However, we will demonstrate that all the existing conditions mentioned in the introduction fail to do so. Let $\theta(t) = \varphi(t)$ (that is defined by ([1.10\)](#page-3-0)). Since

$$
t - 1.002 \le \tau(t) \le \varphi(t) \le t - 1, \quad \frac{1}{e} \le p(t) \le \mu,
$$

we have

$$
\int_{\theta(t)}^{t} p(w) e^{\int_{\tau(w)}^{\theta(t)} p(w_1) e^{\int_{\tau(w_1)}^{w_1} p(w_2) dw_2} dw_1} dw \le \int_{t-1.002}^{t} \mu e^{\int_{w-1.002}^{t-1} \mu e^{\int_{w1-1.002}^{w_1} \mu dw_1} dw} \le e^{-\frac{501\mu}{500}} \left(e^{\frac{251\mu}{250} e^{\frac{501\mu}{500}}} - e^{\frac{\mu}{500} e^{\frac{501\mu}{500}}} \right) < 0.9999,
$$

for all $\mu \leq \frac{1}{e} + 0.205$. Consequently, condition [\(1.7\)](#page-3-1) is not satisfied for all $\mu \leq \frac{1}{e} + 0.205$. Clearly,

$$
\int_{\theta(t)}^{t} p(w) e^{(\lambda(\delta) - \epsilon) \int_{\tau(w)}^{\theta(t)} p(w_1) dw_1} du \leq \int_{t-1.002}^{t} \mu e^{\lambda(\delta) \int_{w-1.002}^{t-1} \mu dw_1} dw
$$

$$
\leq e^{-1 + \frac{251e}{250} \mu} - e^{-1 + \frac{e}{500} \mu} < 0.999
$$

for all $\mu \leq \frac{1}{e} + 0.113$, it follows that condition [\(1.8](#page-3-2)) cannot be applied for all $\mu \leq \frac{1}{e} + 0.113$. In view of

$$
\Psi_0(t) = p(t) \left(1 + \int_{\tau(t)}^t p(w) e^{\int_{\tau(w)}^t p(w_1) e^{\lambda(\delta) \int_{\tau(w_1)}^w p(w_2) dw_2} dw_1} dw \right)
$$
\n
$$
\leq \mu \left(1 + \int_{t-1.002}^t \mu e^{\int_{w-1.002}^t \mu e^{\lambda(\delta) \int_{w_1-1.002}^w \mu dw_2} dw_1} dw \right) < 2.58535
$$

for all $\mu \leq \frac{1}{e} + 0.0794$, we get

$$
\limsup_{t\to\infty}\ \int_{\varphi(t)}^tp(w){\rm e}^{\int_{\tau(w)}^{\varphi(t)} p(w_1)\ {\rm e}^{\int_{\tau(w_1)}^{w_1} p(w_2)\Psi_0(w_2)dw_2}dw_1}dw<1
$$

for all $\mu \leq \frac{1}{e} + 0.0794$. Then we conclude that condition [\(1.9](#page-3-3)) with $n = 0$ can not be applied for $\mu \leq \frac{1}{e} + 0.0794$. Finally, it is clear that

$$
\Omega_1^1(t) \le \int_{\theta(t)}^t p(w) e^{\lambda(\delta) \int_{\tau(w)}^{\theta(t)} p(w_1) dw_1} dw \le \int_{t-1.002}^t \mu e^{e \int_{w-1.002}^{t-1} \mu dw_1} dw < 0.687061
$$

for all $\mu \leq \frac{1}{e} + 0.0184$, so that

$$
C(t) = \frac{1}{1 - \int_{\theta(t)}^t p(w_1) \exp\left(\int_{\tau(w_1)}^{\theta(t)} \frac{p(w_2)}{1 - \Omega_1^1(w_2)} dw_2\right) dw_1} < 4.29043, \quad \text{for all } \mu \le \frac{1}{e} + 0.0184.
$$

Consequently,

$$
\limsup_{t \to \infty} \left(\Omega_1^2(t) + C(\theta(t)) \Omega_2^2(t) \right) < 0.86157 < 1 - B(\delta) = 1 - \frac{1 - \delta - \sqrt{1 - 2\delta - \delta^2}}{2}.
$$

Therefore, condition [\(1.11](#page-4-3)) with $n = 2$ is not satisfied for all $\mu \leq \frac{1}{e} + 0.0184$.

The following example demonstrates the significance of one of our results, especially when $\delta = 0$, and shows that condition (1.6) (1.6) (1.6) is not necessary for the oscillation of Eq. (1.1) (1.1) .

Example 3.2 Consider the differential equation

$$
x'(t) + p(t)x(t-1) = 0, \quad t \ge 1,
$$
\n(3.2)

where

$$
p(t) = \begin{cases} 0 & \text{if } t \in [c_l, d_l] \\ \gamma(t - d_l) & \text{if } t \in [d_l, d_l + 1] \\ \gamma & \text{if } t \in [d_l + 1, d_l + 6] \\ \left(\frac{d_l - t + 6}{c_{l+1} - d_l - 6} + 1\right) \gamma & \text{if } t \in [d_l + 6, c_{l+1}] \end{cases}, \quad l \in \mathbb{N}_0,
$$

where $\gamma \geq 0$, $d_l > c_l + 1$, $c_{l+1} > d_l + 6$ and $\lim_{l \to \infty} c_l = \infty$.

Clearly,

$$
\liminf_{t \to \infty} \int_{\tau(t)}^{t} p(w) dw = \lim_{l \to \infty} \int_{\tau(d_l)}^{d_l} p(w) dw = \int_{d_l - 1}^{d_l} p(w) dw = 0 = \delta.
$$
 (3.3)

From this and ([1.4\)](#page-1-2), it follows in Theorem [2.6](#page-9-5) that $Q_0(t) = 1$.

Let $\theta(t) = \tau(t) = t - 1$, $r_l = d_l + 5$,

$$
I(t) = \int_{\theta(t)}^{t} p(w) e^{\int_{\tau(w)}^{\theta(t)} Q_1(w_1)p(w_1)} dw_1
$$

and

$$
I_1(t) = \frac{\int_t^{\theta^{-1}(t)} p(w) \int_{\tau(w)}^t p(w_1) e^{\int_{\tau(w_1)}^{\theta(t)} p(w_2) Q_1(w_2) dw_2} dw_1 dw}{1 - \int_t^{\theta^{-1}(t)} p(w) dw}.
$$

Therefore,

$$
I_1(r_l) \geq \frac{\int_{d_l+5}^{d_l+6} p(w) \int_{w-1}^{d_l+5} p(w_1) e^{\int_{w_1-1}^{d_l+4} p(w_2) dw_2} dw_1 dw}{1 - \int_{t}^{t+1} p(w) dw} = \frac{e^{\gamma} - \gamma - 1}{1 - \gamma}.
$$

Also

$$
I(r_l) \geq \int_{\theta(d_l+5)}^{d_l+5} p(w) \exp\left(\int_{w-1}^{\theta(d_l+5)} \frac{p(w_1) \exp\left(\int_{w_1-1}^{w_1-1} p(w_2) dw_2\right)}{1 - \int_{w_1-1}^{w_1} p(w_2) \exp\left(\int_{w_2-1}^{w_1-1} p(w_3) dw_3\right) dw_2} dw_1\right) dw
$$

=
$$
\int_{d_l+4}^{d_l+5} \gamma \exp\left(\int_{w-1}^{d_l+4} \frac{\gamma}{1 - \int_{w_1-1}^{w_1} \gamma \exp\left(\int_{w_2-1}^{w_1-1} \gamma dw_3\right) dw_2} dw_1\right) dw
$$

=
$$
\left(e^{\frac{\gamma(e^{\gamma}-1)}{-2+e^{\gamma}}}-2e^{\frac{\gamma}{-2+e^{\gamma}}}-e^{\gamma}+2\right)e^{-\frac{\gamma}{-2+e^{\gamma}}}.
$$

Therefore,

$$
I(r_l) + I_1(r_l) \ge \left(e^{\frac{\gamma(e^{\gamma}-1)}{2+e^{\gamma}}}-2e^{\frac{\gamma}{-2+e^{\gamma}}}-e^{\gamma}+2\right)e^{-\frac{\gamma}{-2+e^{\gamma}}}+\frac{e^{\gamma}-\gamma-1}{1-\gamma} > 1.00054,
$$

for $\gamma = 0.4488$. Then, according to Theorem [2.6](#page-9-5), every solution of Eq. ([3.2](#page-13-1)) is oscillatory for $\gamma = 0.4488$. Observe, however, that $\delta = 0$ and

$$
\limsup_{t \to \infty} \int_{\tau(t)}^{t} p(w)dw = \lim_{l \to \infty} \int_{\tau(d_l + 5)}^{d_l + 5} p(w)dw = \gamma.
$$

That is, none of the results in[[12–](#page-14-5)[14,](#page-14-6) [18,](#page-15-9) [20,](#page-15-10) [30](#page-15-13)[–32\]](#page-15-14) can be applied to Eq. [\(3.2](#page-13-1)) with *γ <* 1.

Acknowledgments

The research of the first author is supported via funding from Prince Sattam bin Abdulaziz University project number (PSAU/2024/R/1445).

References

- [1] Agarwal RP, Berezansky L, Braverman E, Domoshnitsky A. Nonoscillation theory of functional differential equations with applications. Springer, 2012.
- [2] Attia ER, El-Morshedy, HA. New oscillation criteria for first order linear differential equations with non-monotone delays. Journal of Applied Analysis and Computation 2022; 12 (4): 1579-1594.
- [3] Bohner M, Li T. Oscillation of second-order *p*-Laplace dynamic equations with a nonpositive neutral coefficient. Applied Mathematics Letters 2014; 37 (2014): 72-76. https://doi.org/10.1016/j.aml.2014.05.012
- [4] Braverman E, Karpuz B. On oscillation of differential and difference equations with non-monotone delays. Applied Mathematics and Computation 2011; 218 (7): 3880-3887. https://doi.org/10.1016/j.amc.2011.09.035
- [5] Chatzarakis GE, Jadlovská I. Oscillations in differential equations caused by non-monotone arguments. Nonlinear Studies 2020; 27 (3): 589–607.
- [6] Chatzarakis GE, Jadlovská I, Li T. Oscillations of differential equations with non-monotone deviating arguments. Advances in Difference Equations 2019; Paper No. 233, 20: 1687–1839. https://doi.org/10.1186/s13662-019-2162-9
- [7] Džurina J, Grace SR, Jadlovská I, Li T. Oscillation criteria for second‐order Emden–Fowler delay differential equations with a sublinear neutral term. Mathematische Nachrichten 2020; 293 (5): 910-922. https://doi.org/10.1002/mana.201800196
- [8] El-Morshedy HA. On the distribution of zeros of solutions of first order delay differential equations. Nonlinear Analysis 2011; 74 (10): 3353-3362. https://doi.org/10.1016/j.na.2011.02.011
- [9] El-Morshedy HA, Attia ER. New oscillation criterion for delay differential equations with non-monotone arguments. Applied Mathematics Letters 2016; 54: 54-59. https://doi.org/10.1016/j.aml.2015.10.014.
- [10] Elbert Á, Stavroulakis IP. Oscillations of first order differential equations with deviating arguments. Recent trends in differential equations, World Scientific Series in Applicable Analysis 1992; 1: 163-178. *https* : *//doi.org/*10*.*1142*/*9789812798893_0013
- [11] Erbe LH, Zhang BG. Oscillation for first order linear differential equations with deviating arguments, Differential and Integral Equations. An International Journal for Theory and Applications 1988; 1 (3): 305-314.
- [12] Garab A. A sharp oscillation criterion for a linear differential equation with variable delay. Symmetry 2019; 11 (11): 1-10.
- [13] Garab A, Pituk M, Stavroulakis IP. A sharp oscillation criterion for a linear delay differential equation. Applied Mathematics Letters 2019; 93: 58-65. https://doi.org/10.1016/j.aml.2019.01.042
- [14] Garab A, Stavroulakis IP. Oscillation criteria for first order linear delay differential equations with several variable delays. Applied Mathematics Letters 2020; 106: 1-9. https://doi.org/10.1016/j.aml.2020.106366

ATTIA and JADLOVSKÁ/Turk J Math

- [15] Gopalsamy K. Stability and Oscillation in Delay Differential Equations of Population Dynamics. Kluwer Academic Publishers, Dordrecht, 1992.
- [16] Győri I, Ladas G. Oscillation Theory of Delay Differential Equations with Applications. Clarendon Press, Oxford, 1991.
- [17] Infante G, Koplatadze R, Stavroulakis IP. Oscillation criteria for differential equations with several retarded arguments. Funkcialaj Ekvacioj 2015; 58 (3): 347-364. https://doi.org/10.1619/fesi.58.347
- [18] Jaroš J, Stavroulakis IP. Oscillation tests for delay equations. Rocky Mountain Journal of Mathematics 1999; 29 (1): 197-207. https://doi.org/10.1216/rmjm/1181071686
- [19] Jian, C. On the oscillation of linear differential equations with deviating arguments. Mathematics in Practice and Theory 1991; 1: 32-41.
- [20] Kon M, Sficas YG, Stavroulakis IP. Oscillation criteria for delay equations. Proceedings of the American Mathematical Society 2000; 128 (10): 2989-2997. https://doi.org/10.1090/S0002-9939-00-05530-1
- [21] Koplatadze R, Chanturiya T. Oscillating and monotone solutions of first-order differential equations with deviating argument. Differentsial'nye Uravneniya 1982; 18 (8): 1463-1465.
- [22] Koplatadze R, Kvinikadze G. On the oscillation of solutions of first-order delay differential inequalities and equations. Georgian Mathematical Journal 1994; 1 (6): 675-685. https://doi.org/10.1515/GMJ.1994.675
- [23] Ladas G. Sharp conditions for oscillations caused by delays. Applicable Analysis 1979; 9 (2): 93-98. https://doi.org/10.1080/00036817908839256.
- [24] Li T, Frassu S, Viglialoro G. Combining effects ensuring boundedness in an attraction–repulsion chemotaxis model with production and consumption. Zeitschrift für angewandte Mathematik und Physik 2023; 74 (3): 1-21. https://doi.org/10.1007/s00033-023-01976-0
- [25] Li T, Pintus N, Viglialoro G. Properties of solutions to porous medium problems with different sources and boundary conditions. Zeitschrift für angewandte Mathematik und Physik 2019; 70 (3): 1-18. https://doi.org/10.1007/s00033- 019-1130-2
- [26] Li T, Viglialoro G. Boundedness for a nonlocal reaction chemotaxis model even in the attraction-dominated regime. Differential Integral Equations 2021; 34 (5-6): 315-336. https://doi.org/10.48550/arXiv.2004.10991
- [27] Li T, Rogovchenko YV. On the asymptotic behavior of solutions to a class of third-order nonlinear neutral differential equations. Applied Mathematics Letters 2020; 105: 1-7.
- [28] Myshkis, AD. Linear homogeneous differential equations of first order with deviating arguments. Uspekhi Matematicheskikh Nauk 1950; 5 (36): 160-162.
- [29] Philos CG, Sficas YG. An oscillation criterion for first order linear delay differential equations. Canadian Mathematical Bulletin 1998; 41 (2): 207-213. https://doi.org/10.4153/CMB-1998-030-3
- [30] Pituk M. Oscillation of a linear delay differential equation with slowly varying coefficient. Applied Mathematics Letters 2017; 73: 29-36. https://doi.org/10.1016/j.aml.2017.04.019
- [31] Pituk M, Stavroulakis IP, Stavroulakis JI. Explicit values of the oscillation bounds for linear delay differential equations with monotone argument. Communications in Contemporary Mathematics 2023; 25 (03): 2150087. https://doi.org/10.1142/S0219199721500875
- [32] Sficas YG, Stavroulakis IP. Oscillation criteria for first-order delay equations. Bulletin of the London Mathematical Society 2003; 35 (2): 239-246. https://doi.org/10.1112/S0024609302001662