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U(1)-invariant special Lagrangian 3-folds in \mathbb{C}^3 and special Lagrangian fibrations

Dominic Joyce

Abstract

This is a survey of the author's series of three papers [8, 9, 10] on *special Lagrangian 3-folds (SL 3-folds)* in \mathbb{C}^3 invariant under the U(1)-action $(z_1, z_2, z_3) \mapsto (e^{i\theta} z_1, e^{-i\theta} z_2, z_3)$, and their sequel [11] on special Lagrangian fibrations and the SYZ Conjecture.

We briefly present the main results of these four long papers, giving some explanation and motivation, but no proofs. The aim is to make the results and ideas accessible to String Theorists and others who have an interest in special Lagrangian 3-folds and fibrations, but have no desire to read pages of technical analysis.

Let N be an SL 3-fold in \mathbb{C}^3 invariant under the U(1)-action above. Then $|z_1|^2 - |z_2|^2 = 2a$ on N for some $a \in \mathbb{R}$. Locally, N can be written as a kind of graph of functions $u, v : \mathbb{R}^2 \rightarrow \mathbb{R}$ satisfying a nonlinear Cauchy–Riemann equation depending on a , so that $u + iv$ is like a holomorphic function of $x + iy$. When $a = 0$ the equations may have singular points where u, v are not differentiable, which leads to analytic difficulties.

We prove existence and uniqueness results for solutions u, v on domains S in \mathbb{R}^2 with boundary conditions, including singular solutions. We study their singularities, giving a rough classification by *multiplicity* and *type*. We prove the existence of large families of *fibrations* of open subsets of \mathbb{C}^3 by U(1)-invariant SL 3-folds, including singular fibres. Finally, we use these fibrations as local models to draw conclusions about the *SYZ Conjecture* on Mirror Symmetry of Calabi–Yau 3-folds.

1. Introduction

Special Lagrangian submanifolds (SL m -folds) are a distinguished class of real m -dimensional minimal submanifolds in \mathbb{C}^m , which are calibrated with respect to the m -form $\text{Re}(dz_1 \wedge \cdots \wedge dz_m)$. They can also be defined in (almost) Calabi–Yau manifolds, are important in String Theory, and are expected to play a rôle in the eventual explanation of Mirror Symmetry between Calabi–Yau 3-folds.

This paper surveys three papers [8, 9, 10] studying special Lagrangian 3-folds N in \mathbb{C}^3 invariant under the U(1)-action

$$e^{i\theta} : (z_1, z_2, z_3) \mapsto (e^{i\theta} z_1, e^{-i\theta} z_2, z_3) \quad \text{for } e^{i\theta} \in \text{U}(1), \quad (1)$$

and also the sequel [11], which applies their results to study the *SYZ Conjecture* about Mirror Symmetry of Calabi–Yau 3-folds [14].

N
 $N \left\{ z_1, z_2, z_3 \right\}^3 \quad z_3 \quad u(z_3, z_1 z_2),$
 $z_1 z_2 \quad v(z_3, z_1 z_2), \quad |z_1|^2 - |z_2|^2 = a \},$
 $a \in \mathbb{R} \quad u, v \in \mathbb{R}^2 \quad \mathbb{R} \quad N$
 u, v
 $\frac{\partial u}{\partial x} \quad \frac{\partial v}{\partial y} \quad \frac{\partial v}{\partial x} - (v^2 - y^2 - a^2)^{1/2} \frac{\partial u}{\partial y}.$
 $a /$ *elliptic* u, v
 a N $x, \quad v x, \quad v^2 - y^2 - a^2 = 1/2$
 $v x,$ *weak* u, v *singular points* $x,$
 N $(, , x - i u x,)$
 $u - i v$ *nonlinear Cauchy-Riemann equation* u, v
 $x - i y$
 N
 \S
 \S u, v
potential f $\frac{\partial f}{\partial y} = u$ $\frac{\partial f}{\partial x} = v$ f
 $\left(\left(\frac{\partial f}{\partial x} \right)^2 - y^2 - a^2 \right)^{-1/2} \frac{\partial^2 f}{\partial x^2} = \frac{\partial^2 f}{\partial y^2}.$
 N \mathbb{R}^2
 $u_1, v_1 = u_2, v_2$ u_j, v_j j ,
multiplicity $u_1, v_1 \neq u_2, v_2$ \S u, v
 a $u x, -y \equiv u x, y$ $v x, -y \equiv -v x, y$
 u, v x
multiplicity \S \S *types*
 \S \S 3 \S *special*
Lagrangian fibrations *SYZ Conjecture*
ture

2. Special Lagrangian geometry

Yau manifolds m *almost Calabi-*

§

2.1. Special Lagrangian submanifolds in m

calibrated submanifolds

Definition 2.1. M, g *oriented tangent k -plane V*
 M V $T_x M$ M V k
 V V k V M $g|_V$ *volume form*
 $\varphi|_V \leq \alpha \leq T_x N$ x N $\varphi|_V \leq \alpha$ V $\varphi|_V$ *calibration* M α \mathbb{R}
calibrated submanifold $\varphi|_{T_x N}$ $T_x N$ x N k N

minimal submanifolds

§

Definition 2.2. m ω m Ω m z_1, \dots, z_m g
 $g = |z_1|^2 + \dots + |z_m|^2$, $\omega = \frac{i}{2} (z_1 \bar{z}_1 - z_m \bar{z}_m)$,
 $\Omega = z_1 \bar{z}_1 + \dots + z_m \bar{z}_m$.
 m Ω Ω m L m L *special Lagrangian submanifold* m , SL
 m -fold L Ω

Proposition 2.1. *Let L be a real m -dimensional submanifold of m . Then L admits an orientation making it into a special Lagrangian submanifold of m if and only if $\omega|_L \equiv \Omega|_L \equiv$*

m L m *Lagrangian* $\omega|_L \equiv$

$\Omega|_L \equiv$

2.2. Almost Calabi–Yau m -folds and SL m -folds

almost Calabi–Yau manifolds

Definition 2.3. $m \geq 3$ almost Calabi–Yau m -fold (X, J, ω, Ω)
 (X, J, ω, Ω) Calabi–Yau m -fold (X, J, ω, Ω)
 $\omega^m/m - m(m-1)/2 \int_X \omega \wedge \Omega$
 $T_x X \sim g_x, \omega_x, \Omega_x$

special Lagrangian submanifolds

Definition 2.4. (X, J, ω, Ω) special Lagrangian submanifold N
 $\omega|_N \equiv \Omega|_N \equiv 0$
 N compact m -dimensional
 N C^k $k \geq 2$
 N C^∞

3. Background material from analysis

$S \subset \mathbb{R}^n$ domain interior S°
 ∂S boundary $\partial S = S \setminus S^\circ$
 S strictly convex S
 $C^k S$ $k \geq 2$
 $C^\infty S = \bigcap_{k=0}^\infty C^k S$
 $C^{k,\alpha} S$ Hölder space $C^{k,\alpha} S$ $k \geq 0, \alpha \in (0,1)$
 $\partial^k f_\alpha = \frac{|\partial^k f(x) - \partial^k f(y)|}{|x-y|^\alpha}$

second-order quasilinear operator $Q : C^2(S) \rightarrow C^0(S)$

$$(Qu)(x) = \sum_{i,j=1}^n a^{ij}(x, u, \partial u) \frac{\partial^2 u}{\partial x_i \partial x_j} - b(x, u, \partial u),$$

$a^{ij} : S \times \mathbb{R} \times \mathbb{R}^n \rightarrow \mathbb{R}$, $i, j = 1, \dots, n$, $n \times n$ matrix of coefficients Q . Q elliptic if a^{ij} symmetric and $\det(a^{ij}) > 0$. Q divergence form

$$(Qu)(x) = \sum_{j=1}^n \frac{\partial}{\partial x_j} (a^j(x, u, \partial u)) - b(x, u, \partial u)$$

$a^j \in C^1(S \times \mathbb{R} \times \mathbb{R}^n)$, $j = 1, \dots, n$, $b \in C^0(S \times \mathbb{R} \times \mathbb{R}^n)$. Q weak solution $Qu = f$ means $\int_S \psi \frac{\partial Qu}{\partial x_j} = \int_S \psi f$ for all $\psi \in C^1(S)$ with $\psi|_{\partial S} = 0$.

$$-\sum_{j=1}^n \int_S \frac{\partial \psi}{\partial x_j} a^j(x, u, \partial u) = \int_S \psi b(x, u, \partial u) - \int_S \psi f$$

$\psi \in C^1(S)$, $\psi|_{\partial S} = 0$. $Qu = f$

- $Qu = f$ in $C^2(S)$ implies $Qu = f$ in $C^0(S)$
- $Qu = f$ holds with weak derivatives u
- $Qu = f$ holds weakly Q if u is a weak solution once u is known.

a^j, b, f are continuous. Q elliptic $Qu = f$

4. Finding the equations

N

3

$$e^{i\theta} z_1, z_2, z_3 \quad e^{i\theta} z_1, -e^{i\theta} z_2, z_3 \quad e^{i\theta}$$

N

$$N = \{ z_1, z_2, z_3 \in \mathbb{C}^3 \mid z_1 z_2 = v(x, y), \quad |z_1|^2 - |z_2|^2 = a(x, y) \in S \},$$

$$\begin{array}{c}
S \\
|z_1|^2 - |z_2|^2 \\
a \\
N/
\end{array}
\begin{array}{c}
\mathbb{R}^2 \\
a \\
\mathbb{R} \\
u, v \\
S \\
\mathbb{R} \\
moment\ map \\
3 \\
x \\
z_3 \\
y \\
z_1 z_2
\end{array}
\begin{array}{c}
|z_1|^2 - |z_2|^2 \\
3 \\
z_1 z_2
\end{array}$$

Proposition 4.1. Let S, a, u, v and N be as above. Then

If $a \neq 0$, then N is a (possibly singular) special Lagrangian 3-fold in \mathbb{R}^3 if u, v are differentiable and satisfy

$$\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y} \quad \text{and} \quad \frac{\partial v}{\partial x} = (v^2 - y^2)^{1/2} \frac{\partial u}{\partial y},$$

except at points x, y in S with $v = x, y = 0$, where u, v need not be differentiable. The singular points of N are those of the form (x, y, z_3) , where $z_3 = x^2 + y^2$ in S , for $x, y \in S$ with $v = x, y = 0$.

If $a = 0$, then N is a nonsingular special Lagrangian 3-fold in \mathbb{R}^3 if and only if u, v are differentiable in S and satisfy

$$\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y} \quad \text{and} \quad \frac{\partial v}{\partial x} = (v^2 - y^2 - a^2)^{1/2} \frac{\partial u}{\partial y}.$$

$$\begin{array}{c}
\partial u, \partial v \\
\mathbb{R}^3 \\
N \\
T_{\mathbf{z}} N \\
\frac{\partial}{\partial y} \left(\frac{\partial u}{\partial x} \right) \\
\frac{\partial}{\partial x} \left(\frac{\partial u}{\partial y} \right) \\
v \\
\frac{\partial^2 u}{\partial y \partial x} \\
\frac{\partial^2 u}{\partial x \partial y}
\end{array}
\begin{array}{c}
\mathbf{z} \in N \\
, z_3 \\
(|z_1|^2 - |z_2|^2) \\
\mathbf{z} \in \mathbb{R}^3 \\
\mathbf{z} \in T_{\mathbf{z}} N
\end{array}$$

Proposition 4.2. Let S be a domain in \mathbb{R}^2 and $u, v \in C^2(S)$ satisfy $\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}$ for $a \neq 0$. Then

$$\frac{\partial}{\partial x} \left[(v^2 - y^2 - a^2)^{-1/2} \frac{\partial v}{\partial x} \right] = \frac{\partial^2 v}{\partial y^2}.$$

Conversely, if $v \in C^2(S)$ satisfies $\frac{\partial}{\partial x} \left[(v^2 - y^2 - a^2)^{-1/2} \frac{\partial v}{\partial x} \right] = \frac{\partial^2 v}{\partial y^2}$ then there exists $u \in C^2(S)$, unique up to addition of a constant $u = u_0 + c$, such that u, v satisfy $\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}$.

weak solutions $a \neq 0$

N singular solutions

Definition 4.1. S \mathbb{R}^2 $u, v \in C^0(S)$ u, v
singular solution

$$\begin{array}{c}
u, v \\
v \text{ weak solution} \\
a \\
\S
\end{array}
\begin{array}{c}
\frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}, \frac{\partial v}{\partial x}, \frac{\partial v}{\partial y}
\end{array}$$

singular points $u, v \in C^2(S)$ $x \in S$ $v(x) \in S^\circ$
 $C^0(S)$ a $+$ $u_a, v_a \in C^2(S)$ u_a u v_a v
 ∂S u, v \S \S

5. Examples

N \S

Example 5.1. $a \geq$

$$N_a = \left\{ (z_1, z_2, z_3) \in \mathbb{C}^3 \mid |z_1|^2 - a|z_2|^2 - |z_3|^2, (z_1 z_2 z_3) \neq 0, (z_1 z_2 z_3) \geq \right\}.$$

T^2 N_a $\mathcal{S}^1 \times \mathbb{R}^2$ $a >$ N_0 2
 $i\theta_1, i\theta_2$ z_1, z_2, z_3 $-$ $i\theta_1 z_1, i\theta_2 z_2, -i\theta_1 - i\theta_2 z_3$, 2
 \S $u_a, v_a \in \mathbb{R}^2$ \mathbb{R}

Example 5.2. $\alpha, \beta, \gamma \in \mathbb{R}$ $u(x, y) = \alpha x + \beta y + \alpha y + \gamma$
 u, v a

Example 5.3. $u(x, y) = y^2 - x^2 - \frac{1}{2}y^2 - \frac{1}{2}x^2 - \frac{1}{2}x^2$ N u
 v a \S
 m m \mathbb{R}^3

Example 5.4. $u(x, y) = |y| - \frac{1}{2}x$ $v(x, y) = -y - x$ u, v
 $\frac{\partial u}{\partial y}$ N 3 a 3

a *singular solutions* \mathbb{R}^2

6. Generating u, v from a potential f

u, v potential f u, v $\frac{\partial f}{\partial y}$ u
 $\frac{\partial f}{\partial x}$ v $\frac{\partial u}{\partial x}$ $\frac{\partial v}{\partial y}$

Proposition 6.1. *Let S be a domain in \mathbb{R}^2 and $u, v \in C^1(S)$ satisfy (6.1) for $a > 0$. Then there exists $f \in C^2(S)$ with $\frac{\partial f}{\partial y} = u, \frac{\partial f}{\partial x} = v$ and*

$$\left(\left(\frac{\partial f}{\partial x} \right)^2 + y^2 + a^2 \right)^{-1/2} \frac{\partial^2 f}{\partial x^2} = \frac{\partial^2 f}{\partial y^2}.$$

This f is unique up to addition of a constant, $f = f + c$. Conversely, all solutions of (6.1) yield solutions of (6.1).

a

Dirichlet problem

Theorem 6.2. *Suppose S is a strictly convex domain in \mathbb{R}^2 invariant under $x, y \rightarrow x, -y$, and $k \geq 3, \alpha > 0$. Let $a \in \mathbb{R}$ and $\phi \in C^{k+3, \alpha}(\partial S)$. Then if $a > 0$ there exists a unique $f \in C^{k+3, \alpha}(S)$ with $f|_{\partial S} = \phi$ satisfying (6.1). If $a < 0$ there exists a unique $f \in C^1(S)$ with $f|_{\partial S} = \phi$, which is twice weakly differentiable and satisfies (6.1) with weak derivatives.*

Define $u = \frac{\partial f}{\partial y}$ and $v = \frac{\partial f}{\partial x}$. If $a > 0$ then $u, v \in C^{k+2, \alpha}(S)$ satisfy (6.1), and if $a < 0$ then $u, v \in C^0(S)$ are a singular solution of (6.1), in the sense of Definition 6.1. Furthermore, f depends continuously in $C^1(S)$, and u, v depend continuously in $C^0(S)$, on ϕ, a in $C^{k+3, \alpha}(\partial S) \times \mathbb{R}$.

f, u, v

f, u, v ∂S

$|f| \leq \max_{\partial S} |\phi|$ $f' \leq \alpha + \beta x + \gamma y$

S

ϕ a priori $f \in C^1(S)$ u, v

$C^0(S)$ $a > 0$ $v = y$ uniformly elliptic

$f \in C^{k+3, \alpha}(S)$

$f|_{\partial S} = \phi$ a

$f_a \in C^{k+3, \alpha}(S)$ a $C^1(S)$ a + f $f|_{\partial S} = \phi$

a priori f_a

a ,

u, v

singular
entirely unaffected

S°

7. Results motivated by complex analysis

§ § $u_1, v_1 - u_2, v_2$ u_j, v_j
winding number

Definition 7.1. C $\gamma \subset C \setminus \mathbb{R}^2 \setminus \{ \}$
winding number of γ about $\frac{1}{2\pi} \int_C \gamma^* \theta$
 θ $x^{-1} y - y^{-1} x \in \mathbb{R}^2 \setminus \{ \}$

Theorem 7.1. Let S be a domain in \mathbb{C} , and suppose $f : S \rightarrow \mathbb{C}$ is a holomorphic function, with $f \neq 0$ on ∂S . Then the number of zeroes of f in S° , counted with multiplicity, is equal to the winding number of $f|_{\partial S}$ about 0 along ∂S .

multiplicity S°

Definition 7.2. $S \subset \mathbb{R}^2$ $a \in \mathbb{R}$ $u_j, v_j \in C^0(S)$ $j = 1, \dots, n$
 $C^1(S)$ $a \in \mathbb{R}$

$b, c \in S$ zero $u_1, v_1 - u_2, v_2 \in S$ u_1, v_1 u_2, v_2 b, c
 b, c singular $a \in \mathbb{R}$ $v_1 b, v_2 b, b, c$
singular point u_1, v_1 u_2, v_2 b, c nonsingular zero
 b, c isolated $\epsilon > 0$ x, y $u_1, v_1 - u_2, v_2$
 S $\{ (x, y) \in S \mid |x - b|^2 + |y - c|^2 \leq \epsilon^2 \}$
 $b, c \in S^\circ$ $u_1, v_1 - u_2, v_2$ multiplicity b, c
 $\gamma_\epsilon : b, c \rightarrow S$ $\epsilon > 0$ b, c $\epsilon > 0$ $\gamma_\epsilon : b, c \rightarrow S^\circ$
 b, c $u_1, v_1 - u_2, v_2$ $\gamma_\epsilon : b, c$

§

Theorem 7.2. In the situation above, the multiplicity of any isolated zero b, c of $u_1, v_1 - u_2, v_2$ in S° is a positive integer.

b, c

b, c

Proposition 7.3. *In the situation above, suppose $u_1, v_1 - u_2, v_2$ has an isolated, non-singular zero at $(b, c) \in S^\circ$. Then there exists $k \geq 1$ and $C \setminus \{ \}$ such that*

$$\lambda u_1(x, y) - i v_1(x, y) - \lambda u_2(x, y) - i v_2(x, y) = C(\lambda(x - b) - i(y - c))^k O(|x - b|^{k+1} + |y - c|^{k+1}),$$

where $\lambda = \sqrt{(v_1(b, c)^2 - c^2 - a^2)}^{1/4}$.

$$\lambda(b - ic) = \lambda(u_1 - u_2) - i(v_1 - v_2) \quad \lambda(x - b) - i(y - c) \quad \lambda x - iy$$

k multiplicity (b, c) $k \geq 1$

$$j = 0, \dots, k-1 \quad \partial^j u_1(b, c) / \partial^k u_1(b, c) \quad \partial^j u_2(b, c) / \partial^k u_2(b, c) \quad \partial^j v_1(b, c) / \partial^k v_1(b, c) \quad \partial^j v_2(b, c) / \partial^k v_2(b, c)$$

$$u_1, v_1 \not\equiv u_2, v_2 \quad u_1, v_1 - u_2, v_2 \in S^\circ$$

Theorem 7.4. *Let S be a domain in \mathbb{R}^2 , and $a \in \mathbb{R}$. If $a \neq 0$ let $u_j, v_j \in C^1(S)$ satisfy \dots , and if $a = 0$ let $u_j, v_j \in C^0(S)$ be singular solutions of \dots for $j = 0, \dots, k-1$. Then either $u_1, v_1 \equiv u_2, v_2$, or there are at most countably many zeroes of $u_1, v_1 - u_2, v_2$ in S° , all isolated.*

$$u_1, v_1 \not\equiv u_2, v_2 \quad b, c \quad \partial^j u_1(b, c) \quad \partial^j u_2(b, c) \quad u_1, v_1 - u_2, v_2$$

$$\partial^j v_1(b, c) \quad \partial^j v_2(b, c) \quad j \geq 0 \quad u_1, v_1 \equiv u_2, v_2 \quad \partial^k u_1(b, c) / \partial^k u_2(b, c) \quad \partial^k v_1(b, c) / \partial^k v_2(b, c) \quad C \setminus \{ \}$$

$$b, c \quad u_1, v_1 \not\equiv u_2, v_2 \quad u_1, v_1 - u_2, v_2 \in S^\circ$$

$$u, v \quad v \quad x \quad \S$$

Theorem 7.5. *Let S be a domain in \mathbb{R}^2 , and $a \in \mathbb{R}$. If $a \neq 0$ let $u_j, v_j \in C^1(S)$ satisfy \dots for $j = 0, \dots, k-1$, and if $a = 0$ let $u_j, v_j \in C^0(S)$ be singular solutions of \dots for $j = 0, \dots, k-1$. Suppose $u_1, v_1 \neq u_2, v_2$ at every point of ∂S . Then $u_1, v_1 - u_2, v_2$ has finitely many zeroes in S , all isolated. Let there be n zeroes, with multiplicities k_1, \dots, k_n . Then the winding number of $u_1, v_1 - u_2, v_2$ about ∂S is $\sum_{i=1}^n k_i$.*

$$u_j, v_j \quad f_j \quad \S \quad f_j|_{\partial S} \quad \phi_j \quad \partial S \quad k$$

$$\phi_1 - \phi_2 \quad l \quad l \quad \partial S \quad |k| \leq l -$$

Theorem 7.6. Suppose S is a strictly convex domain in \mathbb{R}^2 invariant under x, y and $x, -y$, and a $\mathbb{R}, k \geq, \alpha, l$, and $\phi_1, \phi_2 \in C^{k+3, \alpha} \partial S$. Let $u_j, v_j \in C^0 S$ be the (singular) solution of or constructed in Theorem . from ϕ_j , for $j = 1, 2$.

Suppose $\phi_1 - \phi_2$ has l local maxima and l local minima on ∂S . Then $u_1, v_1 - u_2, v_2$ has finitely many zeroes in S° , all isolated. Let there be n zeroes in S° with multiplicities k_1, \dots, k_n . Then $\sum_{i=1}^n k_i \leq l -$.

$$l \quad u_1, v_1 / u_2, v_2 \quad S^\circ \quad \S$$

8. A rough classification of singular points

$$\S \quad u, v \quad \S$$

Definition 8.1. $S \subset \mathbb{R}^2$ $u, v \in C^0 S$ S x, y $x, -y$ $u', v' \in C^0 S$ $u' x, y = u x, -y$ $v' x, y = -v x, -y$ u', v' u, v b, S $v b,$ $u, v - u', v'$ u, v $isolated$ $u, v - u', v'$ $multiplicity$ $b,$ $u, v \in S^\circ$ $u, v - u', v' = b,$

Theorem 8.1. Let S be a domain in \mathbb{R}^2 invariant under x, y and $x, -y$, and $u, v \in C^0 S$ a singular solution of . If $u x, -y \equiv u x, y$ and $v x, -y \equiv -v x, y$ then u, v is singular along the x -axis in S , and the singularities are nonisolated. Otherwise there are at most countably many singularities of u, v in S° , all isolated.

$$b,$$

$$v x, \quad b,$$

Definition 8.2. $S \subset \mathbb{R}^2$ $u, v \in C^0 S$ $b,$ $u, v \in S^\circ$ $\bar{B}_\epsilon b,$ $\subset S^\circ$ $b,$ $u, v \in \bar{B}_\epsilon b,$ $\epsilon > 0$ $< |x - b| \leq \epsilon$ x, S° $v x, /$ $b - \epsilon, b \times \{ \}$ $b, b \in \epsilon \times \{ \}$ $v x < x - b - \epsilon, b$ $v x > x - b, b \in$ $b,$ *increasing type* $v x > x - b - \epsilon, b$ $v x < x - b, b \in$ $b,$ *decreasing type*

$v(x) < b - \epsilon$, b , maximum type
 $v(x) > b - \epsilon$, b , minimum type

Proposition 8.2. Let $u, v \in C^0(S)$ be a singular solution of $\Delta u = v$ on a domain S in \mathbb{R}^2 , and b_0 be an isolated singularity of u, v in S° with multiplicity k . If b_0 is of increasing or decreasing type then k is odd, and if b_0 is of maximum or minimum type then k is even.

Theorem 8.3. Suppose S is a strictly convex domain in \mathbb{R}^2 invariant under $(x, y) \rightarrow (x, -y)$, and $\phi \in C^{k+3, \alpha}(\partial S)$ for $k \geq 3$ and $\alpha \in (0, 1)$. Let $u, v \in C^0(S)$ be the singular solution of $\Delta u = v$ constructed in Theorem 8.2 from ϕ with $a = 1$.

Define $\phi' \in C^{k+3, \alpha}(\partial S)$ by $\phi'(x, y) = -\phi(x, -y)$. Suppose $\phi - \phi'$ has l local maxima and l local minima on ∂S . Then u, v has finitely many singularities in S° . Let there be n singularities in S° with multiplicities k_1, \dots, k_n . Then $\sum_{i=1}^n k_i \leq l - 1$.

$$j\theta, \quad j\theta \quad S \quad \mathbb{R}^2 \quad \phi$$

Theorem 8.4. There exist examples of singular solutions u, v of $\Delta u = v$ with isolated singularities of every possible multiplicity $n \geq 1$, and with both possible types allowed by Proposition 8.2.

3

§ infinite number $n \geq$ real codimension n

9. Special Lagrangian fibrations

special Lagrangian fibrations

3

SYZ Conjecture §

Definition 9.1. Let $S \subset \mathbb{R}^3$ be a domain invariant under $(x, y, z) \rightarrow (x, -y, z)$. Let $U \subset S$ be a domain with boundary $\partial U \subset \partial S$. Let $f_\alpha \in C^{3, \alpha}(U)$ and $g_\alpha \in C^{3, \alpha}(\partial U)$ be functions satisfying $\Delta f_\alpha = g_\alpha$ in U . Let $u_\alpha = \frac{\partial f_\alpha}{\partial y}$ and $v_\alpha = \frac{\partial f_\alpha}{\partial x}$ be the partial derivatives of f_α with respect to y and x respectively.

$$\begin{aligned}
& u_\alpha, v_\alpha \\
& \alpha \quad a, b, c \quad U \quad C^0 S \quad a \\
& N_\alpha \quad \{ z_1, z_2, z_3 \quad |z_1|^2 - |z_2|^2 = a, \quad x, y \quad S^\circ \}. \\
& N_\alpha \quad 3 \\
& a /
\end{aligned}$$

N_α SL fibration

Theorem 9.1. In the situation of Definition . . . , if α / α' in U then $N_\alpha \cap N_{\alpha'} = \emptyset$. There exists an open set $V \subset \mathbb{R}^3$ and a continuous, surjective map $F: V \rightarrow U$ such that $F^{-1}(\alpha) = N_\alpha$ for all $\alpha \in U$. Thus, F is a special Lagrangian fibration of $V \subset \mathbb{R}^3$, which may include singular fibres.

$$\begin{aligned}
& V \quad \bigcup_{\alpha \in U} N_\alpha \quad \alpha \quad a, b, c \quad \alpha' \quad a', b', c' \quad N_\alpha \quad U \\
& a / a' \quad N_\alpha \cap N_{\alpha'} = \emptyset \quad |z_1|^2 - |z_2|^2 = a \quad N_\alpha \quad a' \quad N_{\alpha'} \quad \partial S \\
& a \quad a' \quad \alpha - \alpha' \quad l \quad u_\alpha, v_\alpha - u_{\alpha'}, v_{\alpha'} \\
& S^\circ \quad N_\alpha \cap N_{\alpha'} = \emptyset \quad N_\alpha \\
& 3
\end{aligned}$$

Example 9.1. S \mathbb{R}^2

$$\begin{aligned}
& \alpha, \quad \phi \in C^{3,\alpha} \partial S \quad U \quad \mathbb{R}^3 \quad \mathbb{R}^3 \quad C^{3,\alpha} \partial S \quad x, y \quad x, -y \\
& \phi \quad bx \quad cy \quad a, b, c / a, b', c' \quad a, b, c - a, b', c' \quad b - b' x \quad c - c' y \quad a, b, c \\
& C^\infty \partial S \quad b - b', c - c' \quad S \quad \partial S \\
& b - b' x \quad c - c' y \\
& V \subset \mathbb{R}^3 \quad S, U \quad F: V \rightarrow \mathbb{R}^3 \quad N_\alpha \quad 3 \\
& \quad \quad \quad c \quad U \quad \mathbb{R}^3 \quad N_\alpha \quad 3 \\
& V \quad \{ z_1, z_2, z_3 \quad |z_1|^2 - |z_2|^2 = a, \quad z_3, \quad z_1 z_2 \quad S^\circ \}.
\end{aligned}$$

Example 9.2. $F: \mathbb{R}^3 \rightarrow \mathbb{R} \times \mathbb{R}^2$

$$\begin{aligned}
& F: z_1, z_2, z_3 \rightarrow a, b, \quad a \quad |z_1|^2 - |z_2|^2 \\
& b \quad \begin{cases} z_3, & a \leq z_1 - z_2, \\ z_3 - z_1 z_2 / |z_1|, & a \geq, \quad z_1 / , \\ z_3 - z_1 z_2 / |z_2|, & a < . \end{cases}
\end{aligned}$$

$$S^1 \times \mathbb{R}^2 \xrightarrow{F^{-1}} a, b \xrightarrow{T^2} \mathbb{C}^3 \xrightarrow{N_{|a|}} \mathbb{C}^3 \xrightarrow{|z_1|, |z_2|} S^1 \xrightarrow{a}$$

10. The SYZ Conjecture

Mirror Symmetry
 X, X

String Theory

$$\begin{array}{c}
 \text{Super Conformal Field Theory} \\
 H^{p,q} X \xrightarrow{X} X \xrightarrow{X} X \\
 \text{not} \\
 H^{1,1} X \xrightarrow{X} X \xrightarrow{\text{mirror}} H^{2,1} X \xrightarrow{X} H^{1,1} X \\
 X
 \end{array}$$

SYZ Conjecture

The SYZ Conjecture. Suppose X and X are mirror Calabi–Yau n -folds. Then (under some additional conditions) there should exist a compact topological n -manifold B and surjective, continuous maps $f: X \rightarrow B$ and $f: X \rightarrow B$, such that

There exists a dense open set $B_0 \subset B$, such that for each $b \in B_0$, the fibres $f^{-1}(b)$ and $f^{-1}(b)$ are nonsingular special Lagrangian n -tori T^n in X and X . Furthermore, $f^{-1}(b)$ and $f^{-1}(b)$ are in some sense dual to one another.

For each $b \in B \setminus B_0$, the fibres $f^{-1}(b)$ and $f^{-1}(b)$ are expected to be singular special Lagrangian n -folds in X and X .

f, f special Lagrangian fibrations
discriminant

X, X

f, f

f, f Lagrangian fibrations
 f, f smooth

generic

almost X f X B

$\frac{f}{X}$ 3

\S

- f X B B
- f X F B
- B \S
- X f X B
- *piecewise smooth* f X B B
- f X B B
- X, X S^1 f X B
- f X B f not B

\S
Acknowledgements:

References

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- Th* $II: G$ Dff G
- T
- Ex* (, 2000)
- \mathbb{C} v v q
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- M v R G . *I.* N
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- v . *III.* *P*
- h
- I
- v – h
- M T

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