

1-1-2005

On A Class of Para-Sakakian Manifolds

CİHAN ÖZGÜR

Follow this and additional works at: <https://journals.tubitak.gov.tr/math>



Part of the [Mathematics Commons](#)

Recommended Citation

ÖZGÜR, CİHAN (2005) "On A Class of Para-Sakakian Manifolds," *Turkish Journal of Mathematics*: Vol. 29: No. 3, Article 4. Available at: <https://journals.tubitak.gov.tr/math/vol29/iss3/4>

This Article is brought to you for free and open access by TÜBİTAK Academic Journals. It has been accepted for inclusion in Turkish Journal of Mathematics by an authorized editor of TÜBİTAK Academic Journals. For more information, please contact academic.publications@tubitak.gov.tr.

On A Class of Para-Sakakian Manifolds

Cihan Özgür

Abstract

In this study, we investigate Weyl-pseudosymmetric Para-Sasakian manifolds and Para-Sasakian manifolds satisfying the condition $C \cdot S = 0$.

Key Words: Para-Sasakian manifold, Weyl-pseudosymmetric manifold.

1. Introduction

Let (M, g) be an n -dimensional, $n \geq 3$, differentiable manifold of class C^∞ . We denote by ∇ its Levi-Civita connection. We define endomorphisms $\mathcal{R}(X, Y)$ and $X \wedge Y$ by

$$\mathcal{R}(X, Y)Z = [\nabla_X, \nabla_Y]Z - \nabla_{[X, Y]}Z, \quad (1)$$

$$(X \wedge Y)Z = g(Y, Z)X - g(X, Z)Y, \quad (2)$$

respectively, where $X, Y, Z \in \chi(M)$, $\chi(M)$ being the Lie algebra of vector fields on M . The Riemannian Christoffel curvature tensor R is defined by $R(X, Y, Z, W) = g(\mathcal{R}(X, Y)Z, W)$, $W \in \chi(M)$. Let S and κ denote the Ricci tensor and the scalar curvature of M , respectively. The Ricci operator \mathcal{S} and the (0,2)-tensor S^2 are defined by

$$g(\mathcal{S}X, Y) = S(X, Y), \quad (3)$$

and

$$S^2(X, Y) = S(\mathcal{S}X, Y). \quad (4)$$

The *Weyl conformal curvature operator* \mathcal{C} is defined by

$$\mathcal{C}(X, Y) = \mathcal{R}(X, Y) - \frac{1}{n-2}(X \wedge SY + SX \wedge Y - \frac{\kappa}{n-1}X \wedge Y), \quad (5)$$

and the *Weyl conformal curvature tensor* C is defined by $C(X, Y, Z, W) = g(\mathcal{C}(X, Y)Z, W)$. If $C = 0$, $n \geq 4$, then M is called *conformally flat*.

For a $(0, k)$ -tensor field T , $k \geq 1$, on (M, g) we define the tensors $R \cdot T$ and $Q(g, T)$ by

$$\begin{aligned} (R(X, Y) \cdot T)(X_1, \dots, X_k) &= -T(\mathcal{R}(X, Y)X_1, X_2, \dots, X_k) \\ &\quad - \dots - T(X_1, \dots, X_{k-1}, \mathcal{R}(X, Y)X_k), \end{aligned} \quad (6)$$

$$\begin{aligned} Q(g, T)(X_1, \dots, X_k; X, Y) &= -T((X \wedge Y)X_1, X_2, \dots, X_k) \\ &\quad - \dots - T(X_1, \dots, X_{k-1}, (X \wedge Y)X_k), \end{aligned} \quad (7)$$

respectively [8].

If the tensors $R \cdot C$ and $Q(g, C)$ are linearly dependent then M is called *Weyl-pseudosymmetric*. This is equivalent to

$$R \cdot C = L_C Q(g, C), \quad (8)$$

holding on the set $U_C = \{x \in M \mid C \neq 0 \text{ at } x\}$, where L_C is some function on U_C . If $R \cdot C = 0$ then M is called *Weyl-semisymmetric* (see [7], [9], [8]). If $\nabla C = 0$ then M is called *conformally symmetric* (see [4]). It is obvious that a conformally symmetric manifold is Weyl-semisymmetric.

Furthermore we define the tensor $C \cdot S$ on (M, g) by

$$(C(X, Y) \cdot S)(Z, W) = -S(\mathcal{C}(X, Y)Z, W) - S(Z, \mathcal{C}(X, Y)W). \quad (9)$$

In [1], T. Adati and K. Matsumoto defined para-Sasakian and special para-Sasakian manifolds which are considered as special cases of an almost paracontact manifold introduced by I. Satō [11]. In the same paper, the authors studied conformally symmetric para-Sasakian manifolds and they proved that an n -dimensional conformally symmetric para-Sasakian manifold is conformally flat and *SP*-Sasakian ($n > 3$). In [5], the authors studied Weyl-semisymmetric para-Sasakian manifolds and they showed that an n -dimensional Weyl-semisymmetric para-Sasakian manifold is conformally flat. In this study, our aim is to obtain the characterizations of the Weyl-pseudosymmetric para-Sasakian manifolds which are the extended class of Weyl-semisymmetric para-Sasakian manifolds and some further characterization of para-Sasakian manifolds satisfying the condition $C \cdot S = 0$.

2. Sasakian and Para-Sasakian Manifolds

Let M be a n -dimensional contact manifold with contact form η , i.e., $\eta \wedge (d\eta)^n \neq 0$. It is well known that a contact manifold admits a vector field ξ , called the *characteristic vector field*, such that $\eta(\xi) = 1$ and $d\eta(\xi, X) = 0$ for every $X \in \chi(M)$. Moreover, M admits a Riemannian metric g and a tensor field ϕ of type (1,1) such that

$$\phi^2 = I - \eta \otimes \xi, \quad g(X, \xi) = \eta(X), \quad g(X, \phi Y) = d\eta(X, Y).$$

We then say that (ϕ, ξ, η, g) is a contact metric structure. A contact metric manifold is said to be a *Sasakian* if

$$(\nabla_X \phi)Y = g(X, Y)\xi - \eta(Y)X,$$

in which case

$$\nabla_X \xi = -\phi X, \quad R(X, Y)\xi = \eta(Y)X - \eta(X)Y.$$

Now we give a structure similar to Sasakian but not having contact.

An n -dimensional differentiable manifold M is said to admit an almost paracontact Riemannian structure (ϕ, ξ, η, g) , where ϕ is a (1,1)-tensor field, ξ is a vector field, η is a 1-form and g is a Riemannian metric on M such that

$$\phi\xi = 0, \quad \eta\phi = 0, \quad \eta(\xi) = 1, \quad g(\xi, X) = \eta(X),$$

$$\phi^2 X = X - \eta(X)\xi, \quad g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y),$$

for all vector fields X and Y on M . The equation $\eta(\xi) = 1$ is equivalent to $|\eta| \equiv 1$, and then ξ is just the metric dual of η . If (ϕ, ξ, η, g) satisfy the equations

$$d\eta = 0, \quad \nabla_X \xi = \phi X,$$

$$(\nabla_X \phi)Y = -g(X, Y)\xi - \eta(Y)X + 2\eta(X)\eta(Y)\xi,$$

then M is called a *Para-Sasakian* manifold or, briefly, a *P-Sasakian manifold*. Especially, a *P-Sasakian* manifold M is called a *special para-Sasakian manifold* or briefly a *SP-Sasakian manifold* if M admits a 1-form η satisfying

$$(\nabla_X \eta)(Y) = -g(X, Y) + \eta(X)\eta(Y).$$

It is known that in a P -Sasakian manifold the following relations hold:

$$S(X, \xi) = (1 - n)\eta(X), \tag{10}$$

$$\eta(\mathcal{R}(X, Y)Z) = g(X, Z)\eta(Y) - g(Y, Z)\eta(X), \tag{11}$$

for any vector fields $X, Y, Z \in \chi(M)$, (see [2], [11] and [12]).

A para-Sasakian manifold M is said to be η -Einstein if

$$\mathcal{S} = aI_d + b\eta \otimes \xi, \tag{12}$$

where \mathcal{S} is the Ricci operator and a, b are smooth functions on M [2].

3. Main Results

In the present section our aim is to find the characterization of P -Sasakian manifolds satisfying the conditions $C \cdot S = 0$ and $R \cdot C = L_C Q(g, C)$.

Firstly we give the following proposition.

Proposition 3.1 *Let M be an n -dimensional, $n \geq 4$, P -Sasakian manifold. If the condition $C \cdot S = 0$ holds on M then*

$$S^2(X, Y) = \left[\frac{\kappa}{n-1} - n + 2 \right] S(X, Y) + [\kappa + n - 1] g(X, Y) \tag{13}$$

is satisfied on M .

Proof. Assume that M is an n -dimensional, $n \geq 4$, P -Sasakian manifold satisfying the condition $C \cdot S = 0$. From (9) we have

$$S(\mathcal{C}(U, X)Y, Z) + S(Y, \mathcal{C}(U, X)Z) = 0, \tag{14}$$

where $U, X, Y, Z \in \chi(M)$. Taking $U = \xi$ in (14) we have

$$S(\mathcal{C}(\xi, X)Y, Z) + S(Y, \mathcal{C}(\xi, X)Z) = 0. \tag{15}$$

So using (5), (10) and (11) we get

$$\begin{aligned}
 0 = & \eta(Y)S(X, Z) - g(X, Y)S(\xi, Z) + \eta(Z)S(X, Y) - g(X, Z)S(\xi, Y) \\
 & - \frac{1}{n-2} \{ S(X, Y)S(\xi, Z) - S(\xi, Y)S(X, Z) + g(X, Y)S^2(\xi, Z) \\
 & - \eta(Y)S^2(X, Z) + S(X, Z)S(\xi, Y) - S(\xi, Z)S(X, Y) \\
 & + g(X, Z)S^2(\xi, Y) - \eta(Z)S^2(X, Y) \} + \frac{\kappa}{(n-1)(n-2)} \{ g(X, Y)S(\xi, Z) \\
 & - \eta(Y)S(X, Z) + g(X, Z)S(\xi, Y) - \eta(Z)S(X, Y) \}.
 \end{aligned}$$

Hence by the use of (4), (10) we find

$$\begin{aligned}
 0 = & \eta(Y)S(X, Z) - (1-n)g(X, Y)\eta(Z) + \eta(Z)S(X, Y) \\
 & - (1-n)g(X, Z)\eta(Y) - \frac{1}{n-2} [-\eta(Y)S^2(X, Z) - \eta(Z)S^2(X, Y) \\
 & + (1-n)^2\eta(Z)g(X, Y) + (1-n)^2\eta(Y)g(X, Z)] \\
 & + \frac{\kappa}{(n-1)(n-2)} [-\eta(Y)S(X, Z) - \eta(Z)S(X, Y) \\
 & + (1-n)\eta(Z)g(X, Y) + (1-n)\eta(Y)g(X, Z)].
 \end{aligned} \tag{16}$$

Thus replacing Z with ξ in (16) and using (4), (10) we obtain

$$\begin{aligned}
 \frac{1}{n-2}S^2(X, Y) = & \left[\frac{\kappa}{(n-1)(n-2)} - 1 \right] S(X, Y) \\
 & + \left[\frac{\kappa}{n-2} + \frac{(n-1)^2}{n-2} - (n-1) \right] g(X, Y),
 \end{aligned}$$

since $n \geq 4$, we get (13). □

Let us consider an η -Einstein P -Sasakian manifold. Then we can write

$$S(X, Y) = ag(X, Y) + b\eta(X)\eta(Y), \tag{17}$$

where X, Y are any vector fields and a, b are smooth functions on M .

Contracting (17), we have

$$\kappa = na + b. \tag{18}$$

On the other hand, putting $X = Y = \xi$ in (17) and using (10) we also have

$$1 - n = a + b. \tag{19}$$

Hence it follows from (18) and (19) that

$$a = 1 - \frac{\kappa}{1-n} \quad , \quad b = \frac{\kappa}{1-n} - n.$$

So the Ricci tensor S of an η -Einstein P -Sasakian manifold is given by

$$S(Y, Z) = \left(1 - \frac{\kappa}{1-n}\right)g(Y, Z) + \left(\frac{\kappa}{1-n} - n\right)\eta(Y)\eta(Z), \quad (20)$$

(For more details see [2]).

Proposition 3.2 *Let M be an n -dimensional, $n \geq 4$, η -Einstein P -Sasakian manifold. Then the condition $C \cdot S = 0$ holds on M .*

Proof. Let M be an η -Einstein P -Sasakian manifold. Since the Weyl tensor C has all symmetries of a curvature tensor, then from (9) it is easy to show that

$$(C(U, X) \cdot S)(Y, Z) = \left(\frac{\kappa}{n-1} + n\right) [\eta(C(U, X)Y)\eta(Z) + \eta(C(U, X)Z)\eta(Y)],$$

for all vector fields U, X, Y, Z on M . So using (5), (10), (11) and (20), by a straightforward calculation, we get $(C(U, X) \cdot S)(Y, Z) = 0$, which proves the proposition. \square

Theorem 3.3 *Let M be an n -dimensional, $n \geq 4$, P -Sasakian manifold. If M is Weyl-pseudosymmetric then M is either conformally flat, in which case M is a SP -Sasakian manifold, or $L_C = -1$ holds on M .*

Proof. Assume that M , ($n \geq 4$), is a Weyl pseudosymmetric P -Sasakian manifold and $X, Y, U, V, W \in \chi(M)$. So we have

$$(\mathcal{R}(X, Y) \cdot \mathcal{C})(U, V, W) = L_C Q(g, \mathcal{C})(U, V, W; X, Y).$$

Then from (6) and (7) we can write

$$\begin{aligned} & \mathcal{R}(X, Y)\mathcal{C}(U, V)W - \mathcal{C}(\mathcal{R}(X, Y)U, V)W - \mathcal{C}(U, \mathcal{R}(X, Y)V)W \\ & - \mathcal{C}(U, V)\mathcal{R}(X, Y)W = L_C [(X \wedge Y)\mathcal{C}(U, V)W - \mathcal{C}((X \wedge Y)U, V)W \\ & \quad - \mathcal{C}(U, (X \wedge Y)V)W - \mathcal{C}(U, V)(X \wedge Y)W]. \end{aligned} \quad (21)$$

Therefore replacing X with ξ in (21) we have

$$\begin{aligned} & \mathcal{R}(\xi, Y)\mathcal{C}(U, V)W - \mathcal{C}(\mathcal{R}(\xi, Y)U, V)W - \mathcal{C}(U, \mathcal{R}(\xi, Y)V)W \\ & - \mathcal{C}(U, V)\mathcal{R}(\xi, Y)W = L_C[(\xi \wedge Y)\mathcal{C}(U, V)W - \mathcal{C}((\xi \wedge Y)U, V)W \\ & \quad - \mathcal{C}(U, (\xi \wedge Y)V)W - \mathcal{C}(U, V)(\xi \wedge Y)W]. \end{aligned} \quad (22)$$

So using (11), (2) and taking the inner product of (22) with ξ we get

$$\begin{aligned} & [1 + L_C][-\eta(Y)\eta(\mathcal{C}(U, V)W) + C(U, V, W, Y) + \eta(U)\eta(\mathcal{C}(Y, V)W) \\ & - g(Y, U)\eta(\mathcal{C}(\xi, V)W) + \eta(V)\eta(\mathcal{C}(U, Y)W) - g(Y, V)\eta(\mathcal{C}(U, \xi)W) \\ & \quad + \eta(W)\eta(\mathcal{C}(U, V)Y) - g(Y, W)\eta(\mathcal{C}(U, V)\xi)] = 0. \end{aligned} \quad (23)$$

Putting $Y = U$ in (23) we have

$$\begin{aligned} & [1 + L_C][C(U, V, W, U) + \eta(W)\eta(\mathcal{C}(U, V)U) \\ & - g(U, U)\eta(\mathcal{C}(\xi, V)W) - g(U, V)\eta(\mathcal{C}(U, \xi)W)] = 0. \end{aligned} \quad (24)$$

So a contraction of (24) with respect to U gives us

$$[1 + L_C]\eta(\mathcal{C}(\xi, V)W) = 0. \quad (25)$$

If $L_C = 0$ then M is Weyl-semisymmetric and so the equation (25) is reduced to

$$\eta(\mathcal{C}(\xi, V)W) = 0, \quad (26)$$

which gives

$$S(V, W) = \left(1 + \frac{\kappa}{n-1}\right)g(V, W) - \left(n + \frac{\kappa}{n-1}\right)\eta(V)\eta(W). \quad (27)$$

Therefore M is an η -Einstein manifold. So using (26) and (27) the equation (23) takes the form

$$C(U, V, W, Y) = 0,$$

which means that M is conformally flat. So by [2], M is a SP -Sasakian manifold.

If $L_C \neq 0$ and $\eta(\mathcal{C}(\xi, V)W) \neq 0$ then $1 + L_C = 0$, which gives $L_C = -1$. This completes the proof of the theorem. \square

So we have the following corollary.

Corollary 3.4 *Every n -dimensional ($n \geq 4$) para-Sasakian is a Weyl-pseudosymmetric manifold of the form $R \cdot C = -Q(g, C)$.*

Acknowledgement

The author would like to thank the referees for their valuable comments and suggestions in the improvement of the paper.

References

- [1] Adati, T. and Matsumoto K., *On conformally recurrent and conformally symmetric P-Sasakian manifolds*, TRU Math., **13**(1977), 25-32.
- [2] Adati, T. and Miyazawa, T., *On P-Sasakian manifolds satisfying certain conditions*, Tensor, N.S., **33**(1979), 173-178.
- [3] Blair, D., *Contact manifolds in Riemannian Geometry*, Lecture Notes in Math. Springer-Verlag, Berlin-Heidelberg-New-York, 509 (1976).
- [4] Chaki, M.C. and Gupta, B., *On conformally symmetric spaces*, Indian J. Math. **5**(1963), 113-122.
- [5] De, U. C. and Guha, N., *On a type of P-Sasakian manifold*, Istanbul Univ. Fen Fak. Mat. Der. **51**(1992), 35-39.
- [6] De, U. C. and Pathak, G., *On P-Sasakian manifolds satisfying certain conditions*, J. Indian Acad. Math. **16**(1994), 72-77.
- [7] Deszcz, R., *Examples of four-dimensional Riemannian manifolds satisfying some pseudo-symmetry curvature conditions*, Geometry and Topology of submanifolds, II (Avignon, 1988), 134-143, World Sci. Publishing, Teaneck, NJ, 1990.
- [8] Deszcz, R., *On pseudosymmetric spaces*, Bull. Soc. Math. Belg., **49**(1990), 134-145.
- [9] Deszcz, R., *On four-dimensional Riemannian warped product manifolds satisfying certain pseudo-symmetry curvature conditions*, Colloq. Math. **62**(1991), no. 1, 103-120.
- [10] Deszcz, R. and Hotlos, M., *Remarks on Riemannian manifolds satisfying a certain curvature condition imposed on the Ricci tensor*, Prace Nauk. Pol. Szczec., **11**(1989), 23-34.
- [11] Satō, I., *On a structure similar to the almost contact structure*, Tensor, N.S., **30**(1976), 219-224.
- [12] Satō, I. and Matsumoto, K., *On P-Sasakian manifolds satisfying certain conditions*, Tensor, N.S., **33**(1979), 173-178.

ÖZGÜR

- [13] Szabó, Z. I., *Structure theorems on Riemannian spaces satisfying $R(X, Y) \cdot R = 0$ I the local version*, J. Diff.Geom. **17**(1982) 531-582.
- [14] Yano, K. and Kon, M., *Structures on Manifolds*, Series in Pure Math., Vol 3, World Sci., 1984.

Cihan ÖZGÜR
Balıkesir University,
Faculty of Arts and Sciences,
Department of Mathematics,
10100 Balıkesir-TURKEY
e-mail: cozgur@balikesir.edu.tr

Received 15.01.2004