Effect of Pitching Delta Wing on Vortex Structures with and without Impingement Plate

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Abstract

Flow past the leading edge of a delta wing oscillating about its mid-cord in a pitch plane with a reduced frequency of $K=0.74$ generates primary vortices having mostly elongated shapes. Their shapes and orientations vary with the pitching angle of the delta wing in upstroke and downstroke directions. Unsteady flows around the impingement plate placed downstream of the delta wing and in the flow field downstream of the onset of vortex breakdown are characterized by the existence of unsteady large- and small-scale vortices. These time-dependent vortex core formations and breakdowns apply aerodynamic loads to the impingement plate. For the pitching delta wing, the development of the vortex core and degree of hysteresis are found to be a strong function of reduced frequency.

Key words: PIV, Delta wing, Vortex breakdown, Angle of attack, Pitching

Introduction

Improved understanding of unsteady flow phenomena, especially from a fundamental fluid dynamics aspect, is essential in order to develop an effective control scheme. In this sense, control of vortex breakdown continues to be of vital importance because the breakdown may have a considerable effect on aerodynamic behavior such as aircraft performance where unsteadiness may affect the stability of an aircraft and also cause buffeting.

Comprehensive reviews of experimental and theoretical descriptions of various aspects of the vortex breakdown process were given by Hall (1972), Leibovich (1978, 1984), Escudier (1988) and Rockwell (1998). The structure of vortex breakdown was studied by Lambourne and Bryer (1961), Sarpkaya (1971) and Faler and Leibovich (1977) using traditional flow visualization techniques. The most recent reviews on vortex breakdown were done by Mitchell and Delery (2001) and Negro and Doherty (2001).

The effect of shear layer control on leading edge vortices over delta wings with a sharp leading edge was investigated by McCormick and Gursul (1996). This type of flow was also numerically studied by Hammond and Redekopp (1994), Gad el-Hak and Blackwelder (1987) and Gordnier and Visbal (1995).

The force testing of small-scale models in a water tunnel was investigated by Atlee et al. (1998) to obtain static and dynamic forces and moment data representative of full-scale fighter aircraft maneuvering in the post-stall regime. A review of experimental data for a delta wing under both steady and unsteady conditions was presented from a vortex dynamics point of view by Lee and Ho (1990). Conclusions were derived that vortices on the suction surface provide an important contribution to the lift of a delta wing, especially for those with a large sweep back angle.

Şahin et al. (2001) indicated that a substantial retardation, or delay, in the onset of vortex breakdown, and thereby development of a large-scale concentration of vorticity, are attainable when the leading edge of the impingement plate positioned in the
wake-flow region is perturbed at a natural frequency of vortex breakdown. Akllı et al. (2001) used the technique of high-image-density Particle Image Velocimetry to characterize the alterations and structure of the leading edge vortex formed from a delta wing at high angle of attack in the presence of a small wire oriented transversely to the axis of the vortex. It was demonstrated that an extremely small wire having a diameter two orders of magnitude smaller than the diameter of the leading edge vortex prior to the onset of vortex breakdown can substantially advance the onset of breakdown by as much as fifteen vortex diameters. It was indicated that the effectiveness of a wire at a given diameter is a strong function of the location of the wire along the axis of the vortex.

The unsteady structure of flow on a delta wing subjected to controlled motion has received less attention. Leading edge vortices due to low Reynolds number flow past a pitching delta wing were examined by Atta and Rockwell (1990). They oscillated the delta wing sinusoidally over a range of tenfold reduced frequency in order to determine the nature of the vortex development and breakdown. They found that the vortex core develops in the upstream direction towards the apex at low frequencies. On the other hand, there is an ejection of the leading edge of the vortex core from the apex in the downstream direction at high frequencies. They defined reduced frequency as $K = \frac{f_C}{f_e}$. This dimensionless frequency represents the ratio of the wing chord $C$ to the wavelength $U_\infty/f_e$ of the forced motion, where $U_\infty$ is the freestream (reference) velocity and $f_e$ is the frequency of the delta wing. They examined the flow structure over the range of reduced frequency $0.025 < K < 1.94$ and mean angle of attack $5^\circ < \alpha_m < 20^\circ$. It is known that a delta wing in steady flow can provide high lift at large angles of attack and are therefore used on many high-performance aircraft.

Gad el-Hak and Ho (1985) studied the flow field around two pitching delta wings with apex angles of 90° and 60°, at chord Reynolds number up to $3.5 \times 10^5$. The reduced frequency was in the range $K = 0.05$ to 3. They reported that the threedimensional separation process of the leading edge vortex starts from the trailing edge corners and propagates upstream and inward. At low reduced frequencies, the separation region on the suction side is fairly thick. A distinct change of the flow pattern happens at $K = \pi$. In the work of LeMay et al. (1990) a sharp-edged, flat-plate delta wing having a sweep angle of 70° was used. The wing was sinusoidally pitched about its one-half chord position at reduced frequency ranging from $K = 0.025$ to 0.15 at root chord Reynolds numbers between $9 \times 10^4$ and $3.5 \times 10^5$ for angle of attack ranges of $\alpha = 29^\circ$ to $39^\circ$ degree and $\alpha = 0^\circ$ to $45^\circ$. The hysteresis and an overshoot are observed in the chordwise position of vortex breakdown at a reduced frequency as low as $K = 0.025$. As the reduced frequency is further increased the hysteresis effect becomes greater. Özgören et al. (2001a) investigated the vortex generation of a stationary and pitching delta wing in the presence of the stationary impingement plate by acquiring images of flow in side-view and end-view planes. They observed that the mechanism of vortex-plate interaction varies substantially. Features of the partitioned vorticity field are also interpreted in terms of space-time distributions of vertical (transverse) velocity above and below the impingement plate. The magnitude of the buffet velocity distribution is found to be sensitive to the elevation from the top or bottom surface of the impingement plate. Shih and Ho (1994) had a stationary two-dimensional NACA 0012 airfoil placed at the static stall angle of 12° in a sinusoidally varying free stream. They introduced a local circulation measurement technique to survey the evolving vorticity field on the airfoil and showed that the aerodynamic properties were closely related to the change of circulation as a result of the balance between vorticity convection and generation from the surface. The vorticity produced by the spatial variation of the pressure gradient always cancels the vorticity convection of the boundary layer. Therefore, the surface vorticity flux generated by the temporal change of the surface pressure dominates the dynamics of the attached flow.

The aim of the present investigation is to study the patterns of vortex development under the effect of a pitching motion of a delta wing with and without an impingement plate placed in the wake flow region using a scanning laser version of high-image density Particle Image Velocimetry.

**Measurement Techniques and Experimental System**

Experiments were carried out in a recirculating, free-surface water channel located in Lehigh University, Fluid Mechanics Laboratory, USA. The water channel test section was constructed of transparent Plexiglas with upstream and downstream PVC reservoirs,
which had a cross section of 927 mm x 610 mm. The free-surface of the water was maintained at a height of 558.8 mm. The water flow speed was controlled by an axial flow pump, which provided reliable test section flow speeds of 2.0 cm/s to 38 cm/s. A honeycomb, which had an area ratio of 2:1, was located immediately upstream of contraction. This flow conditioning provided very low levels of turbulence intensity in the test section. All experiments were performed at a speed of $U_\infty = 42$ mm/s and the Reynolds number was around $Re = 9.4 \times 10^3$ based on a chord of 222.3 mm delta wing.

A schematic of the experimental system used in the present investigation is shown in Figure 1. The delta wing used had a chord length of $C = 222.3$ mm at a sweep angle of $\Lambda = 75^\circ$. The thickness of the delta wing was 3.18 mm. It was beveled at an angle of 34° on its windward side. The impingement plate had a length of $L_p = 162$ mm and a thickness of $t_p = 6.35$ mm. The distance between the trailing edge of the delta wing and the leading edge of the impingement

\[ a(t) = \alpha_m + \alpha_o \sin(\Omega t) \]
\[ \alpha_m = 20^\circ, 24^\circ \text{ and } 30^\circ \]
\[ \alpha_o = 10^\circ \]
\[ T_e = 22.54 \text{ s} \]

Figure 1. Schematics of delta wing subjected to high-amplitude oscillations about its mid-chord and the impingement plate. Dimensions are in mm.
plate was maintained at $L = 73$ mm. Both the delta wing and the impingement plate were mounted in separate sections, placed between two 12 mm thick false walls, and spaced 508 mm apart to facilitate installation in the water channel test section. The front edges of the false walls were beveled in order to provide sharp edges, which minimize flow disturbance. The delta wing and the impingement plate were placed at the mid distance between the free surface and the bottom wall of the channel, which were 560 mm apart. The delta wing was connected to a driving mechanism so that it could be driven in its a pitch plane independently.

The delta wing was sinusoidally oscillated about its mid-cord in a pitch plane to provide a vortex core that convects downstream and impinges upon the leading edge of the sharp-edged impingement plate, as seen in Figure 1. A step motor controlled the oscillation amplitude and frequency of the delta wing motion. The variation of angle is defined as \( \alpha(t) = \alpha_m + \alpha_o \sin(\omega_e t) \) where \( \omega_e = 2\pi f_e \). The period \( T_e = 2\pi/\omega_e \) and the time interval between images were \( T_e = 22.54 \) s and 0.644 s, respectively.

In the present study, a high-powered Argon Ion laser with a 20 watt power output was used. The laser sheet was created by passing the laser beam through a steering mirror and a focusing lens combination onto a 8-facet rotating mirror to create a vertical side view scanning laser sheet. The 8-faceted mirror rotated at a frequency of 9.38 Hz, giving a scanning frequency of 75 Hz. The frequency and amplitude of the oscillating mirror were controlled by an optical scanner and its amplifier. A rotating mirror scanning frequency of 75 Hz allowed a Canon Eos-1 camera to photograph 5 exposures of the metallic coated seeding particles when the camera shutter speed was 1/15 s. The magnification factor of the camera lens was 1:4.3. A bias mirror placed in front of the camera lens at 45° to the optical axis of the camera could be activated to superimpose artificial uniform velocity (bias velocity) on the flow. In other words, the bias mirror oscillated at 3.33 Hz with the desired amplitude of 0.30 V while the camera shutter was open; this added a positive displacement to all particles in the free stream direction.

The film used for particle images was 35 mm Kodak Tmax, with a resolution of 300 lines per millimeter, which was digitized at a resolution of 125 pixel/mm. A single frame cross-correlation technique was employed to determine the velocity field. Each image was mapped into a regular mesh of overlapping interrogation windows size of 90 by 90 pixels. An overlap ratio of 0.5 was used in order to satisfy the Nyquist sampling criterion. This resulted in a grid spacing of 61 mm on the negative or 76 mm in the actual flow field. The grid size was 61 × 94, resulting in 5734 velocity vectors in an actual field size of 142 mm × 92 mm.

**Discussion of Experimental Results**

**Vortex Breakdown Hysteresis**

In this section of the study, the dynamic behavior of the leading edge vortices with and without an impingement plate was investigated using dye visualization and PIV to define the position of the onset of vortex breakdown. As seen in Figure 1, \( X_{vb} \) specifies the distance between onset of vortex breakdown and apex of a delta wing. The onset of vortex breakdown distance \( X_{vb} \) is normalized by delta wing chord length \( C \) as \( X_{vb}^* = X_{vb}/C \). A delta wing was sinusoidally pitched about its mid-chord with a reduced frequency of \( K = 0.74 \) for mean angles of attack of \( \alpha_m = 20°, 24° \) and 30° with an amplitude of \( \alpha_o = 10° \).

Non-dimensional onset of vortex breakdown locations are presented as a function of angles of attack in Figure 2 for a pitching cycle along with static data obtained over the same angles of attack range and free stream velocity. Before explaining the results, it is worth mentioning that the required time for full relaxation of the breakdown to its equilibrium position does not appear to correlate with the pitching rate. Because, the delta wing subjected to a pitching motion with a reasonably high reduced frequency induces phase shift between the delta wing motion and the onset of vortex breakdown. Figure 2 gives a graphical representation of how the location of vortex breakdown varies not only between the upstroke and the downstroke of a given motion, but also how it differs from the static results for three different mean angle of attack values. A study of the dynamic behavior of the leading edge vortices on a delta wing undergoing oscillatory pitching motion with a reduced frequency ranging from \( K = 0.05 \) to 0.3 was presented by LeMay et al. (1990). The delta wing was oscillated in a sinusoidal fashion in the angles of attack range between 29° and 39°. The hysteresis they observed had a 2% difference with the static cases. In the present experiment, the existence of a dynamic hysteresis in the vortex flow relative to the static case is shown in Figure 2. Here, the results
Comparisons of static and dynamic loops of vortex breakdown as a function of angle of attack. Amplitude of oscillation angle of attack is $\alpha_m = 10^\circ$, period of oscillation is $T_e = 22.54$ s and the reduced frequency is $K = 0.74$.

of hysteresis with plate (WP) and without plate (WOP) are compared. The hysteretic behavior is generally the same for both the WP and WOP cases. In the third diagram in Figure 2, the results of vortex breakdown locations are presented as closed loops. This indicates that vortex breakdown never disappears from the entire flow field range considered in the present experiment. On the other hand, setting...
the mean angles of attack to 20° and 24° force the vortex breakdown locations to move further downstream and disappear completely during the downstroke of the vortex core axis. When a delta wing is pitched, there is a time lag in the response of the vortex flow structure, which can result in temporally delayed vortex formation at low angle of attack or temporarily delayed vortex breakdown at higher angle of attack values. By taking advantage of these unsteady effects, a high performance aircraft might be able to perform certain maneuvers more quickly and efficiently (LeMay et al., 1990). The mechanism of aerodynamic hysteresis for sinusoidally oscillating delta wing was investigated by Huang et al. (1994). An unsteady model of a vortex system was developed to simulate the phenomena of aerodynamic hysteresis of sinusoidally perturbed delta wings. They concluded that the flow separation on the wing surface strongly depends on the reduced frequency and direction of the pitching motion. As the wing pitches up, the flow separation on the wing surface is suppressed. It is well known that the phase shift existing in the flow field strongly depends on the dimensionless reduced frequency $K$ relative to that occurring for the stationary delta wing. In the present experiment, the discrepancy between the static and dynamic onset of vortex breakdown values is significantly high due to the high-reduced frequency $K$. As seen in Figure 2, for delta wings undergoing cyclic motions, with $K = 0.74$, a hysteresis is developed in the location of vortex breakdown flow with high rate of discrepancy relative to the static case.

The angle difference between the static angle of attack of the delta wing and vortex core region axis is 8° as shown in Figure 3a. This angle is independent of the angle of attack. During the experiment of static angle of attack, considerable time was given to let the flow reach the equilibrium state. Figure 3b presents the phase difference between pitching delta wing axis and vortex core axis with respect to the case of the stationary wing. The angle of the attack of the vortex core region in the horizontal plane was calculated by fitting a straight line through the center of core region in each image. There is a high level of variation in the angle of attack of the vortex core axis corresponding to the pitching delta wing position. However, angle differences between the axis of vortex core region and pitching delta wing occur during the upstroke and downstroke motion of the delta wing. Finally, it can be stated that the maximum and minimum angle differences are 16° and 9°, respectively, as seen in Figure 3b.

### Instantaneous Vortex Structure of a Pitching Delta Wing

The structure of vortex breakdown using standard flow visualization techniques does not provide a precise definition of the complex three-dimensional unsteady structure of the flow. The present experimental study seeks to describe the unsteady flow structure above or below (depending on the angle of attack) the pitching delta wing and along the impingement plate for static and dynamic angles of attack. During one cycle of wing oscillation, 36 images were taken in the period of $T_c = 22.54$ s. Instantaneous vorticity distributions, $\omega$, during the pitching motion with an amplitude of $\alpha_0 = 10^\circ$ are presented in Figures 4 and 5. Patterns of instantaneous positive and negative vorticity, $\omega$, are indicated as a solid line and dashed line, respectively. Minimum and incremental values of these positive (solid line) and negative (dashed line) instantaneous vortices are $\omega_{\text{min}} = \pm 1.5$ s$^{-1}$ and $\Delta \omega = 0.75$ s$^{-1}$ respectively. Nominal angle of attack of the delta wing is $\alpha_m = 30^\circ$ and amplitude of perturbation angle of attack is $\alpha_0 = 10^\circ$. The onset of vortex breakdown appears at $X_{cb}/C = 0.97$ and the central axis of the vortex core is positioned above the impingement plate for the pitching angle of attack of the delta wing $\alpha(t) = 30^\circ$ as seen in image N = 1 in Figure 4a. As indicated in the second and third images in Figure 4a, the location of the vortex breakdown advances upstream towards the leading edge of the delta wing rapidly. The axis of the vortex core region moves upward and downward with the pitching motion of the delta wing. After a certain period of time, for example, by $t^* = tU_\infty/C = 0.85$ or $t = 4.508$ s, vortex breakdown propagates rapidly upstream to a location close to the leading edge of the delta wing, which is around $X_{cb}/C = 0.6$ as seen in Figure 2. This result corresponds to the image N = 8 of Figure 4a. During this propagation, vortices elongate in the longitudinal direction. Counter-rotating vortices are developed around the primary vortices, which impinge the leading edge of the plate as well. Özgören et al. (2001b) stated that a total of five distinct vorticity layers of a stationary delta wing are detectable in the absence of vortex breakdown at low angles of attack. Small-scale concentrations of opposite signs in the external layers of the main vertical regions appear to form a counter-rotating system. It was previously stated that in an impinging jet, the ring-shaped coherent structure in the shear layer in-
duces counter-rotating vortices while it approaches the walls (Gad el-Hak and Ho, 1985). In the present experiment, the animation of 36 instantaneous vorticity images showed that counter-rotating vortices appear clearly beyond the vortex breakdown location and move downstream. It is worth mentioning that during pitching of the delta wing, rounded shaped vortices are generated by the trailing edge of the delta wing, which is designated as the trailing edge vortex (tev) indicated in Figure 4b. During the pitching motion, there are intersections between the vortex core axis and the impingement plates. As a result of these intersections, impinging vortices periodically induce a high rate of unsteady aerodynamic

Figure 3a. Comparison of static angle of attack of delta wing and of an axis of a vortex core region.

Figure 3b. Comparison of pitching angle of attack of a delta wing and of an axis of a vortex core region in the presence of the impingement plate. Amplitude of oscillation angle is $\alpha_\alpha = 10^\circ$, nominal angle of attack is $\alpha_m = 30^\circ$ and oscillation period is $T_e = 22.54$ s.
loading on the leading edge of the impingement plate. Images $N = 16$, $N = 24$ and $N = 32$ in Figure 4b illustrate that the vortex breakdown core region moves downstream during the downstroke motion of the delta wing. The existence of unsteady large- and small-scale vortices characterize the unsteady flow around the delta wing. In practical cases, these aerodynamic loads may interact with the wing struc-
tural response causing aeroelastic instabilities, which may restrict, for example, the aircraft flight envelope. The offset between the instantaneous location of vortex core and the delta wing and degree of hysteresis in relation to the static values of the delta wing were found to be a strong function of the reduced frequency.

**Figure 4b.** Excerpts from cinema sequence showing evolution of patterns of instantaneous positive (solid line) and negative (dashed line) vorticity $\omega$. Minimum and incremental values of instantaneous vorticity are $\omega_{\text{min}} = \pm 1.5 \, s^{-1}$ and $\Delta \omega = 0.75 \, s^{-1}$. 
Figures 5a and 5b present instantaneous vorticity distributions in the absence of the WOP case. Images presented in time sequence demonstrate the mechanism of the development and collapse of the vortex core during the pitching motion of the delta wing. In fact, in this experiment, attention was focused on the primary (major) vortex formed from the leading edge of the wing and counter-rotating vortex.
vortices developed near the boundary of the primary vortex core region. Using the laser-sheet technique, it is possible to visualize not only the primary vortex addressed in the foregoing section, but also the small-scale vortices, presented in Figures 4 and 5. Atta and Rockwell (1990) investigated the leading edge vortices of a pitching delta wing in order to allow examination of the flow structure. They used

**Figure 5b.** Excerpts from cinema sequence showing evolution of patterns of instantaneous positive (solid line) and negative (dashed line) vorticity. Minimum and incremental values of instantaneous vorticity are $\omega_{\text{min}} = \pm 1.5 \, \text{s}^{-1}$ and $\Delta \omega = 0.75 \, \text{s}^{-1}$. 


different visualization techniques, such as dye injection and hydrogen bubble methods. They stated from their dye visualization experiments that the primary vortex is fed by vorticity from the boundary layer along the leading edge of the delta wing. The secondary vortex adjacent to leading edge is fed by vorticity shed from the edge. In the present experiment, a quantitative observation was done to provide more information in detail. Throughout Figures 4 and 5 primary vortices are designated as $Q^+$ and $Q^-$ vortices developed during the over shooting process are designated as $Q^{+}_0$ and $Q^{-}_0$ and counter-rotating vortices are designated as $C_1^+, ..., C_3^+, C_1^- ... C_3^-$. Examining all images in Figures 4 and 5, it may be seen that the onset of vortex breakdown moves forward and backward in the flow direction rapidly. In some of the images, vortex breakdown location advances well upstream beyond the left boundary of the images close to the delta wing apex. Therefore, indicating all of the locations of vortex breakdown in terms of instantaneous vortices of PIV readings is not possible during a complete pitching cycle. During the pitching motion of the delta wing, primary vortices designated as $Q^+$ and $Q^-$ elongate substantially in the longitudinal direction.

Existence of the impingement plate in the flow field expands the size of the cross section of the vortex core region compared to the WOP case. Figures 4a and 4b demonstrate that moving the delta wing upstroke direction from the position $N = 1$ corresponding to the mean angle of attack of $\alpha(t) = 30^\circ$ to a position $N = 8$ corresponding to the angle of attack $\alpha(t) = 39.5^\circ$, the location of vortex breakdown advances upstream rapidly. At $N = 8$ ($\alpha(t) = 39.5^\circ$) elongated primary vortices $Q^+$ and $Q^-$ demonstrate that the onset of vortex breakdown sheds forward in a short period of time. This type of vortex core phenomenon observed in each set of tests (a total of three sets) during the experiment were discussed by Özgören (2000) in detail. The level of vorticity shown in Figures 4a and 4b in the experiment of the WP case is more or less equal to the level of vorticity shown in Figures 5a and 5b in the experiment of the WOP case. During the downstroke motion the onset of vortex breakdown is substantially retarded, i.e. it moves downstream. Moreover, this retardation process continues until the delta wing reaches an angle of attack of $\alpha(t) = 30^\circ$ in the upstroke motion. In the image $N = 1$ in Figure 5a, the peak values of vorticity in the vortex breakdown region are dramatically reduced since onset of vortex breakdown location moves further downstream. The results in Figure 5a indicate that the diameter of the cross section of the vortex core is smaller when the impingement plate is removed from the flow field.

**Instantaneous velocity distributions**

Contours of instantaneous velocity (magnitudes of velocity vectors) distributions in the vicinity of a vortex core region as a function of a pitching angle of attack, $\alpha_m = 30^\circ$, are shown in Figures 6 and 7 for the WP and WOP cases, respectively. Numbers on the contours correspond to velocity in mm/s; incremental value between the contours is 2.5 mm/s. The solid line represents positive instantaneous constant velocity distributions and the dashed line represents negative instantaneous constant velocity distributions that are in the opposite direction of positive velocity. The nominal angle of attack of delta wing is $\alpha_m = 30^\circ$ and amplitude of perturbation angle of attack of the delta wing is $\alpha_p = 10^\circ$. The top image in Figure 6a indicates that during the upstroke motion of delta wing at $\alpha_m = 30^\circ$ negative velocity region occurs at $X_{\text{hub}} = C$. The decay of the instantaneous velocity of V prior to the onset of vortex breakdown is relatively mild. This negative velocity core region, in which appears downstream of onset of vortex breakdown, advances upstream rapidly during the upstroke motion of the vortex core axis. The final image in Figure 6a indicates that overshoot of vortex breakdown occurs causing a large area of negative velocity. In image $N = 16$ in Figure 6b wake-type the flow dominates the large area of the flow field. Here, instantaneous velocity is presented to indicate a magnitude of wakeflow regions and to also show the non-uniformity of local velocity distribution in the entire flow field. Images $N = 24$ and 32 in Figure 6b clearly indicate that the size of area illustrating the non-uniform velocity distribution is reduced during the downstroke motion of the vortex core axis relative to the pitching motion of the delta wing. Image $N = 32$ in Figure 6b illustrates the onset of vortex breakdown location quite well, although one frame of instantaneous velocity is used. It is worth mentioning that there is no possibility to present averaged velocity contours due to the pitching motion of the delta wing. This motion changes flow properties locally in each instant of time. Similar results are also presented in Figures 7a and 7b for the WOP experiment. In general, the distribution of local velocity contours in the absence of the...
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Impingement plate is the same as the distribution of velocity contours in the presence of the impingement plate. The image of N = 16 in Figure 7b shows that the negative velocity occupies a larger area compared to the WP cases shown in Figure 6a. As seen in images 8 and 16 in Figures 5a and 5b, primary vortices have elongated geometrical shapes that lay throughout the flow field causing reversed flow. The identical data shown in the top image in Figure 7b is presented in Figure 8 as distributions of velocity.

**Figure 6a.** Contours of constant instantaneous velocity V for the case of the delta wing subjected to a high-amplitude oscillation at period $T_e = 22.54$ s.
Vectors. During the overshoot flow process, a high rate of flow circulation occurs along the wake flow axis shown in this figure.

Concluding Remarks

At higher angles of attack ranging from 10° to 40°, dimensionless vortex breakdown locations from the apex of the delta wing $X_{vb}$ yield larger hysteresis
loops with $\alpha$ (t). The size of these hysteresis loops decrease with decreasing angles of attack ranging from $\alpha = 40^\circ$ to $\alpha = 10^\circ$. Time-dependent vortex-core formation and breakdown may apply aerodynamic loads on the plate. These aerodynamic loads may interact with the plate structural response causing aeroelastic instability. Atta and Rockwell (1990) stated that the timing of vortex development relative to

**Figure 7a.** Contours of constant instantaneous velocity $V$ for the case of the delta wing subjected to a high-amplitude oscillation at period $T_e = 22.54$ s.
to the delta wing position is a strong function of the reduced frequency. As a consequence of the phase shift associated with the vortex development during the pitching delta wing motion relative to that occurring for the stationary delta wing, the nearest location of vortex breakdown to the apex occurs near the maximum angle of attack of the delta wing in the upstroke pitching motion. Structures of the vor-
tex core as a whole take a variety of forms strongly dictated by the pitching motion of the delta wing. During the upstroke motion of the vortex core axis, the onset of vortex breakdown overshoots rapidly towards the apex of the delta wing. When the position of the onset of vortex breakdown is stable, the breakdown occurs in a bubble mode. During the downstroke motion of the delta wing, after a short while the vortex core axis also moves downward causing retardation of vortex breakdown. At this instant, the onset of vortex breakdown moves downstream in a classical spiral mode. Once the location of the breakdown is stable, it switches from spiral mode to the bubble mode randomly or visa versa. These observations are seen in the experiments of mean angles of attack $\alpha_m = 20^\circ, 24^\circ$ and $30^\circ$ for the WP and WOP cases. An offset occurs between the central axis of the vortex core and the instantaneous position of the pitching delta wing. Since the reduced frequency is quite high, a substantial hysteresis occurs in the plot of $X_{vb}/C$ against $\alpha(t)$ at a reduced frequency of $K = 0.74$. The instantaneous velocity contours indicate that velocity distributions vary throughout the entire image as a function of pitching angle of attack of the delta wing. They give further information on the development of the primary vortices. During the overshoot of onset of vortex breakdown negative velocity distributions occupy a large range of area in close regions of the trailing edge of the delta wing.

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**Nomenclature**

- $C$: chord of delta wing (mm)
- $f_e$: oscillation frequency (Hz), $f_e = 1/T_e$
- $K$: dimensionless reduced frequency, $K = \pi f_e C/ U_\infty$
- $L$: distance between trailing edge of the delta wing and leading edge of the plate (mm)
- $L_p$: length of the plate (mm)
- $T$: time (s)
- $t^*$: dimensionless time $t^* = t U_\infty/C$
- $Re$: Reynolds number, $Re = U_\infty C/\nu$
- $T_e$: period of oscillation (s)
References


